

Smart Train collision Prevention and Monitoring System using IoT Chinmaya C¹, Aniketh B², Ms. Radha Korimani³, Ankith Samuel C⁴, Darshan N⁵

^{1,2,4,5} UG Student, ³Assistant Professor, Department of Computer Science and Engineering AMC Engineering College Banglore, India chinmayac09@gmail.com, aniketh6351@gmail.com, kradha.rymec@gmail.com ankithsamuelc@gmail.com, darshandhanu9729@gmail.com

ABSTRACT

Train collisions and accidents are among the major concerns in railway transportation, often leading to severe damage and loss of life. This project presents an IoT-based Smart Train Collision Prevention and monitoring System that utilizes real-time sensor data and cloud connectivity to enhance railway safety. The system consists of two train models, each equipped with an ESP32 microcontroller and various sensors to detect obstacles, monitor fuel levels, and calculate train speed.

This project aims to enhance the railway safety by enabling early detection of potential hazards and providing real-time monitoring through cloud connectivity. The proposed system offers a cost-effective and efficient solution to prevent train collisions and improve railway management.

I. INTRODUCTION

Railway transportation is one of the most widely used and efficient modes of travel, but it also comes with safety challenges including train collision, derailments and fuel shortages. Traditional railway safety system rely heavily on human supervision and predefined signalling mechanisms, which may not always be sufficient to prevent accidents. The increasing demand for automation and real-time monitoring in railways systems calls for smarter and more reliable solutions.

The project "Smart Train Collision Prevention and Monitoring System using IoT" aims to enhance railway safety by integrating IoT-based technology with real-time cloud monitoring. The system consists of two train models, each equipped with an ESP32 microcontroller and various sensors to monitor train parameters. An ultrasonic sensor detects oncoming trains to prevent collisions, while a water level sensor ensures adequate fuel levels for uninterrupted operations. The ADXL345 accelerometer detects sudden impacts or derailments, and a potentiometer measures acceleration to calculate train speed.

To provide real-time monitoring alerts, the system is connected to Google Firebase, where sensor data is stored and accessed remotely. A buzzer and an I2C LCD display provide immediate warnings in case of emergencies. Additionally, a station master application, developed using MIT app Inventor, allows railway authorities to track train conditions and take preventive measures when necessary.

By implementing IoT and cloud-based monitoring, this system offers a cost-effective, efficient, and scalable solution for train collision prevention and railway management. It not only enhances safety but also provides valuable data insights for future improvements in railway automation.

II. WORKING PRINCIPLE

The **smart Train Collision Prevention and monitoring System** is designed around the **ESP32 microcontroller**, which manages the entire system by collecting and processing data from various sensors and controlling outputs. Its built-in Wi-Fi module allows real-time data to be uploaded to the **Google Firebase** cloud platform.

At the core of collision detection is the **ultrasonic sensor**, which continuously measures the distance between the train and any object in its path. If another train or obstacle is detected within a critical range, the system instantly activates the **buzzer** to alert the operators and updates the Firebase database to reflect the potential threat.

The **water level sensor** plays a key role in monitoring the simulated fuel tank of the train. It ensures the fuel level remains adequate, if it drops below a threshold, the system triggers an alert. The **ADXL345 accelerometer** monitors train movement and senses sudden jerks, vibrations, or tilts, which can indicate collisions or derailments. This motion data is analysed and shared with the Firebase server, helping in real-time accident detection and reporting.

The **potentiometer** is used as a speed control simulator. It adjusts the input to the ESP32, which calculates the train's acceleration. Based on this, the system estimates and logs the train's speed, contributing to performance tracking and safety assurance.

The I2C LCD display is used onboard each train to present real-time data such as distance from obstacles, speed, fuel level and emergency alerts, ensuring immediate visibility for maintenance personnel or demo purposes.

To complete the system, a user-friendly Android application developed using **MIT App Inventor** allows railway authorities or station masters to monitor both train models in real-time. The app displays key sensor readings, alert messages, and current speed, and provides a platform for quick decisions in case of emergency scenarios.

Together, the combination of these hardware components and software platforms creates a reliable, responsive system that enhances railway safety by preventing collisions.

III. COMPONENTS AND SPECIFICATIONS

A. ESP32 Microcontroller

The ESP32 is a powerful microcontroller with built in Wi-Fi and Bluetooth connectivity. It serves as the brain of the system, collecting data from all sensors, processing it, and sending real-time updates to the cloud via Firebase. *B. Ultrasonic sensors*(*HC-SR04*)

This sensor is used to measure the distance between the train and any obstacle or oncoming train. It sends out ultrasonic waves and calculates the distance based on the time it takes for the echo to return. It plays a crucial role in preventing collision.

C. Water level sensor

This sensor monitors the train's fuel tank level (simulated in the model). If the level drops to low, it sends a signal to a lot the system, ensuring the train doesn't run out of operational power.

D. ADXL345 Accelerometer

A 3-axis accelerometer that detects sudden movements or vibrations, indicating derailments or collisions. It provides valuable motion data to help assess the train's safety condition.

E. Potentiometer

The potentiometer is used to simulate throttle control. It provides analog values corresponding to the train's acceleration. These values are used to estimate the speed of the train.

Additionally, the buzzer provides audio alerts to signal potential dangers such as a nearby train, low fuel, or abnormal acceleration. It serves as an immediate warning mechanism for on board or remote users.

I2C 16x2 LCD Display shows real time data such as fuel level, speed, collisions alerts, and other important system information. It provides clear and continuous status updates directly from the train.

Google Firebase acts as a cloud database where all sensor data is sent and stored. It allows for Realtime monitoring of the train system from a remote location and facilitates timely responses to emergencies.

MIT App Inventor application is a mobile application built using MIT App inventor allows station masters or railway authorities to remotely monitor each train status, receive alerts, and take prompt action in emergencies. It is user friendly and accessible on android devices.

IV. PROPOSED SYSTEM

A IoT based smart train collision prevention and monitoring system is designed to enhance railway safety through real time sensor data acquisition and cloud connectivity. The system consists of two train models, each equipped with an ESP32 microcontroller, sensors and an IoT-enabled monitoring framework to ensure proactive hazard detection and efficient railway management. It allows to take preventive measure and helps to save lives. This real time monitoring provides accurate information about the railway systems and operate remotely.

A. Collision detection prevention

An Ultrasonic sensor is employed to detect the presence of an oncoming train on the same track. Upon detection, an alert is triggered to prevent collisions. The integration of real-time communication between trains and railway authorities ensures immediate action to mitigate risks. The interconnectivity between trains and railway authorities ensure swift communication, reducing the likelihood of accidents caused by human error or mechanical failures.

B. Opertional monitoring performance analysis

To maintain smooth train operations, the system incorporates a water level sensors to continuously monitors fuel level. By preventing unexpected fuel shortages, this feature ensures uninterrupted services and enhances operational efficiency. Additionally an ADXL345 accelerometer is deployed to identify sudden impacts or derailments, providing real-time alerts to railway authorities. This allows for immediate investigation and response, minimizing potential damage and passenger risk. A potentiometer is utilized to measure train acceleration, which, when processed to use appropriate algorithms, enables accurate speed calculation essential for maintaining safe travel conditions.

C. Intelligent Alerting and Data Visualization

To enhance user experience and improve situational awareness, a buzzer and an I2C LCD display provide realtime alerts and status updates to train operators and railway controllers. The intuitive display system ensures that critical warning related to potential hazards, abnormal speed fluctuations or sensor detection are immediately communicated. Additionally, all collected sensor data is stored in Google Firebase, allowing for continuously

IJARSE ISSN 2319 - 8354

monitoring and retrieval of historical records.

D. Cloud-Based Monitoring and Railway Management

The system is integrated with a remote monitoring application, developed using MIT App Inventor, enabling station masters and railway authorities to oversee train condition in real-time. Through the cloud-based dashboard, operators can visualize strange telemetry data, analyze past incidents, and implement necessary preventive measures. The seamless integration of IoT and cloud computing ensures a scalable and efficient infrastructure for railway management, reducing maintenance costs and improving safety measures.

E. Impact and Future Scope

By leveraging IoT and cloud based monitoring, the proposed system is significantly enhance railway safety by enabling early detection of potential hazards and providing real-time data analytics. The cost-effective design, combined with an easy-to-use monitoring application, allows railway authorities to optimize operations, minimize enhancements may involve expanding the system to include AI-driven predictive maintanance, automated emergency breaking mechanisms, and enhaced wireless communication protocols to further improve railway transportation safety. From this we can enable real time monitoring the railway system movements over a period of time and can take the precaution.

ULTRASONIC SENSOR Fireb POTENTIOMETRIC SENSOR ESP32 SOIL SENSOR LCD BUZZER ACCELOMETRIC SENSOR

Fig. 1. Model Block Diagram

Fig. 1. Shows that the ESP32 microcontroller surrounded by different sensors such as Ultrasonic, Potentiometric, Soil moisture and Accelerometer sensors also connected to a real-time database called Google Firebase.

V. SYSTEM ARCHITECTURE

The system architecture follows a modular and layered design, consisting of four main components: sensor nodes, processing and control unit, cloud database, and user interface. At the lowest level, sensors continuously monitor the physical environment and operational parameters of the train. These sensors are interfaced with the ESP32 microcontroller, which processes the input data, identifies hazardous conditions, and triggers local and remote alerts accordingly.

The ESP32 acts as the central node, performing edge computing tasks such as calculating speed, detecting collisions, and formatting data packets for transmission. It uploads this data to the Firebase real-time cloud, which

BLOCK DIAGRAM

serves as the centralized platform for data logging and synchronization. The cloud ensures that the system's status is accessible at any moment from anywhere, facilitating real-time supervision and analysis. The final layer is the Android mobile application, which queries the Firebase database and presents a user-friendly dashboard to railway authorities or monitoring staff. This structured architecture ensures robustness, scalability, and ease of maintenance.

VI. EXISTING SYSTEM

The current railway safety mechanisms are largely traditional and reactive, making real-time accident prevention difficult. Train operations primarily rely on signalling systems, human supervision, and station-based communication, often leading to delayed responses, inefficient monitoring, and increased risks. The traditional signalling and communication systems, including fixed track signals, manual station controls, and radio communication, do not provide automated warnings in case of emergencies such as brake failures or obstacles, increasing the likelihood of collisions due to signal failures or misinterpretations.

Additionally, there is no automated obstacle and collision detection system, forcing train operators to rely solely on their visual perception, which becomes unreliable in adverse conditions like dense fog, heavy rain, or night-time operations. This limitation makes high-speed rail networks particularly vulnerable, as manual reaction time is often insufficient.

Fuel monitoring and efficiency tracking remain a challenge, as diesel-powered locomotives only undergo fuel level checks at designated stations, leading to possible delays when a train unexpectedly runs low on fuel. The lack of automated tracking prevents railway authorities from analysing fuel consumption patterns, inefficiencies, or potential wastage, which could otherwise help optimize resources.

In terms of accident detection and emergency response, railway personnel often become aware of derailments or collisions only after a manual report from the driver or another train operator. This delay is further exacerbated in remote areas with weak communication signals, preventing timely rescue operations. There is no automated system to detect abrupt acceleration, sudden impacts, or derailments, which could trigger immediate alerts to control rooms. Inefficient speed monitoring and braking systems pose additional risks, as train speed and acceleration are managed manually, relying on the driver's experience rather than real-time sensor inputs. The absence of automated braking systems limits swift responses to sudden obstacles or approaching trains. Furthermore, there is no centralized real-time data storage and monitoring system, meaning train operational data—including speed, acceleration, fuel levels, and collision alerts—is not accessible to railway authorities. The inability to track multiple trains remotely prevents network-wide safety monitoring, and the lack of historical records complicates accident investigations, hindering efforts to analyse speed fluctuations, braking activity, and sensor alerts.

VII. FUTURE SCOPE

The Smart Train Collision Prevention and Monitoring System holds great potential for future enhancements and large-scale deployment in real railway networks. One major improvement could be the integration of GPS modules to accurately track train location and speed in real-time, providing precise geolocation data that enhances monitoring and route management.

To overcome the limitations of Wi-Fi dependency, the system can be upgraded to support LoRa WAN or GSM modules, allowing it to operate effectively over longer distances and in remote areas without stable internet access.

This would make the solution more viable for real-time communication in widespread railway networks. The use of machine learning algorithms and data analytics on historical sensor data stored in Firebase could predict potential failures, analyse accident patterns, and automate responses, improving safety through predictive maintenance and intelligent alerts. For more robust obstacle detection, the ultrasonic sensor could be replaced or supplemented with LIDAR or infrared sensors, which offer better range, precision, and performance under varying environmental conditions. These sensors can be integrated to develop a more reliable hazard detection system. The station master application built with MIT App Inventor can be enhanced using professional development platforms like Flutter or Android Studio, offering better user interfaces, enhanced performance, stronger security, and more complex features like map-based tracking and emergency controls. On the hardware side, the system can be scaled to support multiple train units and centralized control stations, facilitating communication between trains and infrastructure like stations, crossings, and signal systems using IoT-based V2I (Vehicle-to-Infrastructure) communication.

Moreover, integrating battery management systems and solar panels for power autonomy in sensor units can ensure uninterrupted operation during long journeys or in case of power failures, making the system more self-sustainable. With the right support and partnerships with railway authorities, this prototype could evolve into a cost-effective commercial safety solution, promoting safer railway transportation not only in developed regions but also in rural and developing areas with minimal existing infrastructure.

CONCLUSION

The Smart Train Collision Prevention and Monitoring System holds great potential for future enhancements and large-scale deployment in real railway networks. One major improvement could be the integration of GPS modules to accurately track train location and speed in real-time, providing precise geolocation data that enhances monitoring and route management.

In conclusion, the IoT-based Smart Train Collision Prevention and Monitoring System demonstrates a promising approach to enhancing railway safety through real-time monitoring, obstacle detection, and cloud-based data management. By integrating sensors such as ultrasonic detectors, water level sensors, accelerometers, and potentiometers with the ESP32 microcontroller, the system effectively detects potential hazards, monitors train status, and provides timely alerts to prevent accidents. The use of Firebase for cloud connectivity and the mobile application built with MIT App Inventor allows for seamless monitoring by railway authorities, enabling quick response in critical situations.

Although currently implemented on a prototype scale, the project offers strong foundational potential for real-world applications. With future upgrades in hardware, communication protocols, and software scalability, this system can evolve into a practical, cost-efficient safety solution for modern railway systems. Ultimately, the project not only addresses safety concerns but also emphasizes the role of smart technologies in transforming transportation infrastructure for a safer and more efficient future.

The template will number citations consecutively within brackets [1]. The sentence punctuation follows the bracket [2]. Refer simply to the reference number, as in [3]—do not use "Ref. [3]" or "reference [3]" except at the beginning of a sentence: "Reference [3] was the first ..."

Number footnotes separately in superscripts. Place the actual footnote at the bottom of the column in which it was

cited. Do not put footnotes in the abstract or reference list. Use letters for table footnotes.

Unless there are six authors or more give all authors' names; do not use "et al.". Papers that have not been published, even if they have been submitted for publication, should be cited as "unpublished" [4]. Papers that have been accepted for publication should be cited as "in press" [5]. Capitalize only the first word in a paper title, except for proper nouns and element symbols.

For papers published in translation journals, please give the English citation first, followed by the original foreignlanguage citation [6].

REFERENCES

- [1] G. Eason, B. Noble, and I. N. Sneddon, "On certain integrals of Lipschitz-Hankel type involving products of Bessel functions," Phil. Trans. Roy. Soc. London, vol. A247, pp. 529–551, April 1955. (references)
- J. Clerk Maxwell, A Treatise on Electricity and Magnetism, 3rd ed., vol. 2. Oxford: Clarendon, 1892, pp.68– 73.
- [3] I. S. Jacobs and C. P. Bean, "Fine particles, thin films and exchange anisotropy," in Magnetism, vol. III, G. T. Rado and H. Suhl, Eds. New York: Academic, 1963, pp. 271–350.
- [4] K. Elissa, "Title of paper if known," unpublished.
- [5] R. Nicole, "Title of paper with only first word capitalized," J. Name Stand. Abbrev., in press.
- [6] Y. Yorozu, M. Hirano, K. Oka, and Y. Tagawa, "Electron spectroscopy studies on magneto-optical media and plastic substrate interface," IEEE Transl. J. Magn. Japan, vol. 2, pp. 740–741, August 1987 [Digests 9th Annual Conf. Magnetics Japan, p. 301, 1982].
- [7] M. Young, The Technical Writer's Handbook. Mill Valley, CA: University Science, 1989.
- [8] K. Eves and J. Valasek, "Adaptive control for singularly perturbed systems examples," Code Ocean, Aug. 2023. [Online]. Available: https://codeocean.com/capsule/4989235/tree
- [9] D. P. Kingma and M. Welling, "Auto-encoding variational Bayes," 2013, arXiv:1312.6114. [Online]. Available: https://arxiv.org/abs/1312.6114
- [10] S. Liu, "Wi-Fi Energy Detection Testbed (12MTC)," 2023, gitHub repository. [Online]. Available: https://github.com/liustone99/Wi-Fi-Energy-Detection-Testbed-12MTC
- [11] "Treatment episode data set: discharges (TEDS-D): concatenated, 2006 to 2009." U.S. Department of Health and Human Services, Substance Abuse and Mental Health Services Administration, Office of Applied Studies, August, 2013, DOI:10.3886/ICPSR30122.v2