



Design and Analysis of HG 25 Gear Box For Marine Engine

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ABSTRACT

Marine engines are responsible for Driving of the vessel from one port to another. Whether it's of a small ship plying in the coastal areas or of a massive one voyaging international waters A gearbox Consume 35 % of external forces and transmits power from two engines operating with different speeds This the Paper Showing the design, & manufacturing of helical gears for marine Operations aim behind this design is low weight and more accuracy gears. Such gear box is Available in fishing boat in which marine engine is used. It requires high load carrying capacity, strength, torque Also it must be operated efficiently. There are various types of engines are available which are ranges from 220HP to 500HP and for this engine 10 to 12 types of gear box are available. We are going to design the gear box for 500 HP engine and then analysis to check the performance of engine

Keywords: *Marine Engine Wear Stress Torque analysis*

1. Introduction

The main function of a marine gearbox system is to develop and transmit the torque over the required speeds. The paper showing the work of design a gear train system which transmit a power of 500 HP and 2000 RPM. A gear is rotating machine part which transmit torque with the help of cut teeth, which mesh with another. Gear influence the speed, magnitude and direction of power source. When two gears meshes with different no. of teeth giving mechanical advantage is produced with both the rotational speeds and the torques of both differentiating in a simple relationship. this engines is operated with high speeds and large stresses also with deflections in the gears & rotating component. For the safe functioning of engine, these two factors have to minimize. In this work, structural analysis on a high speed helical gear used in marine engine have been carried out. The main aim in this Paper is designing the Gear train for HG 25 gearbox which withstand at high speed and high load. Also operate marine engine efficiently and smooth for different condition, and increases its working life read these instructions carefully.

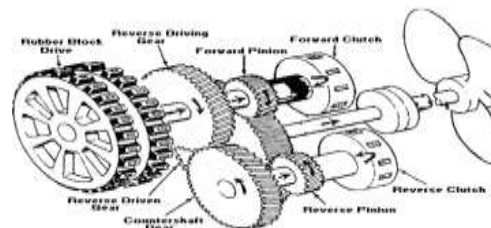


Figure 1 Typical gear box marine engine



2. Objectives

The main My aim in this project is to design Gear Box for HG 25 for 500HP, gear box which should not be fail at high speed and high load. For fishing, boats need to stay longer time in the sea so our aim is to operate marine engine efficiently and smooth for different conditions, and increases its working life.

3. Design and Calculations

Design Calculations

- Design for Single Stage Gear box: As normal pressure angle (ϕ_n) = 25°

Helix angle $\psi = 15^\circ$

Pinion speed $N_p = 2000$ rpm Centre Distance = 261mm

- Calculate actual number of teeth We have reduction ratio 3:1

$$Z_p = 31$$

$$Z_g = 95$$

Speed of output shaft $N_g = N_1/i$

$$= 666.66$$

- Calculate face width (b) $b = 1.15 \times \pi \times M_n / \sin(15)$ $b = 55.83$

- Calculate virtual number of teeth For pinion

$$Z'_p = Z_p / \cos^3 \psi$$

$$= 34.39$$

For gear

$$Z'_g = Z_g / \cos^3 \psi$$

$$= 105.41$$

Calculate lewis form factor

$$Y'_p = 0.484 - (2.87/Z'_p) \quad Y'_p = 0.4005$$

$$Y'_g = 0.456$$

- Decide Pinion is weaker or gear S_{ut} for EN353 = 835

$$\sigma_b = \frac{S_{ut}}{3}$$

$$03$$

$$\sigma_b = 278.33$$

$$(\sigma_b)_p * Y'_p = 111.47 \quad (\sigma_b)_g * Y'_g = 126.91$$

So pinion is weaker

- Calculate Beam Strength $S_b = (\sigma_{bp} * Y'_p) * M_n * b$ $S_b = 24893.48$

Calculate wear strength

$$S_w = \frac{d_p * b * k * Q}{\cos 2\tau}$$

$$d_p = (Z_p M_n) / \cos \tau$$

$$= 128.37 \quad b = 55.83 \quad k = 6.7600$$

$$Q = 2 Z_g / (Z_g + Z_p) \quad Q = 1.508$$

$$S_w = 78305$$



- Tangential load Factor

- - $P_t = P$

V

$P = 372.85 \text{ Kw}$

$V = 13.44 \text{ m/s}$
 $P_t = 27.74 \text{ N}$

- Calculate Effective Load based on primary estimation $P_{eff} = (C_s/C_v) P_t$

$C_s = 2$

$C_v = 5.6$

$5.6 + \sqrt{V}$

$C_v = 0.60436$

Hence $P_{eff} = 91.800 \text{ N}$ Now for safe Design $P_{eff} * FOS < S_w$

- Error in pinion, for grade

$E_p = 8 + 0.63(M_n + 0.25 \times \sqrt{d_p})$

$= 12.30 \text{ micron}$
 $E_p = 0.0123 \text{ mm}$
 $E_g = 0.013 \text{ mm}$
 $e = E_p + E_g$

$= 0.0123 + 0.013 = 0.0253$

- Deformation factor (c) $C = 11500 * e$

$= 297.85$

- Maximum tangential load $P_{tmax} = C_s * k_m * P_t$

$K_m = 1$

$P_{tmax} = 55.4800$

- Calculation for Dynamic load (F_d)

$F_d = \frac{21(bc + F_{tmax})}{21v + (\sqrt{bc + F_{tmax}})}$

$F_d = 15122 \text{ N}$

$P_{eff} = P_{tmax} + F_d = 15419.85 \text{ N}$

For safe design, $P_{eff} * FOS < S_w$
 $23129 < 78305$

Design is safe

CAD Model of Drive Pinion



Figure 2 CAD Model Pinion Isometric view

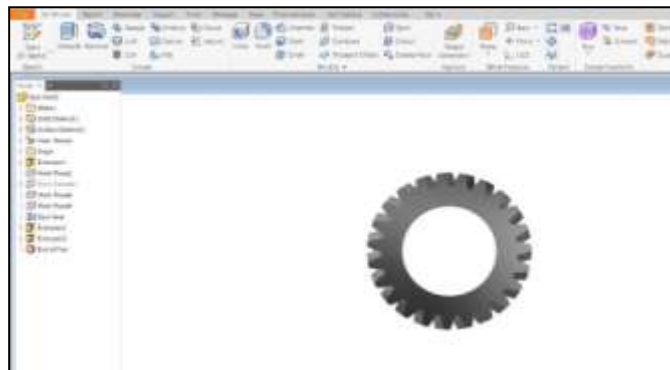


Figure 3 Front View CAD pinion

Stress & Deformation Analysis of Drive Pinion Von Mises Stress Analysis

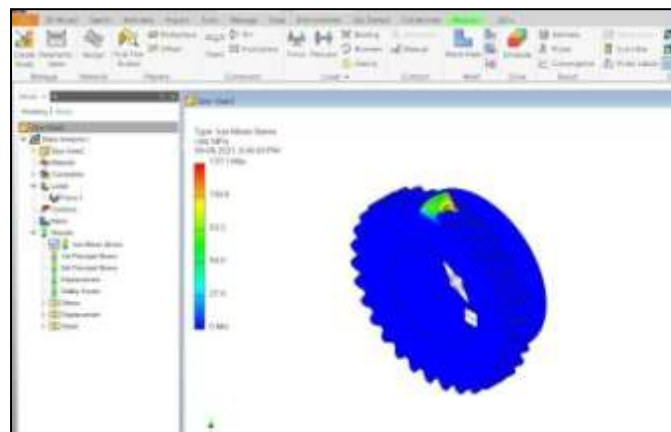


Figure 4 Stress Analysis of Pinion

Deformation Analysis

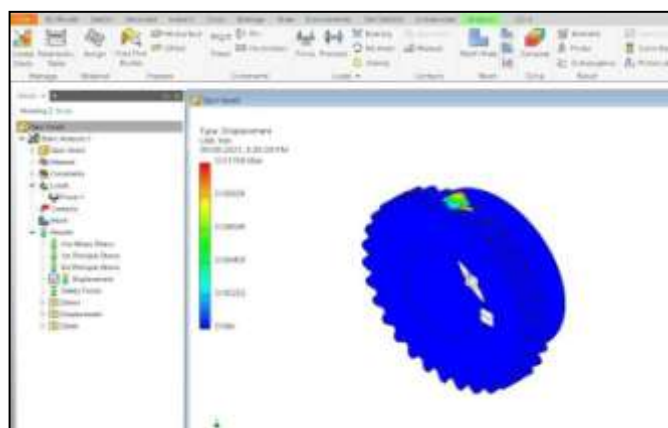


Figure 5 Deformation Analysis of Pinion



CAD Model of Output gear

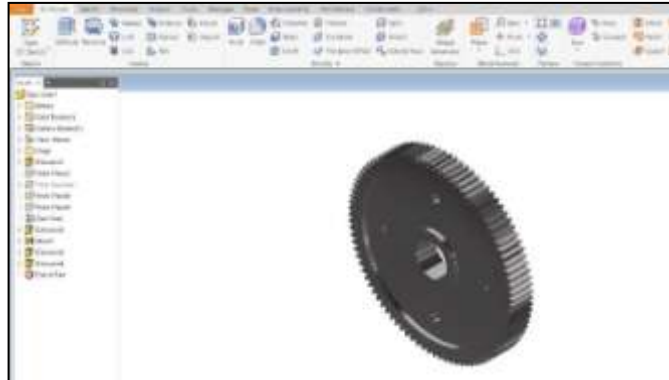


Figure 6 CAD Model of Output Gear Isometric View

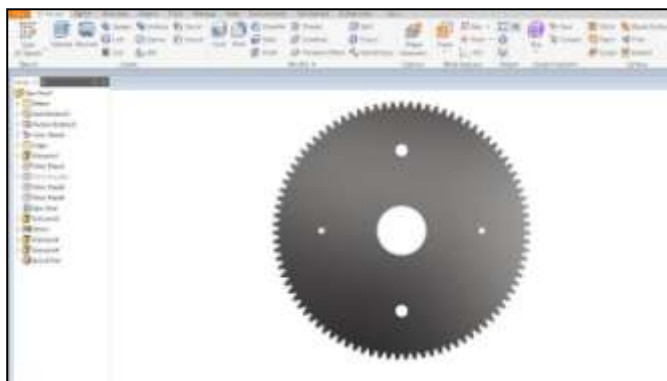


Figure 7 CAD Model of Output Gear Front View

Stress & Deformation Analysis of Output Gear

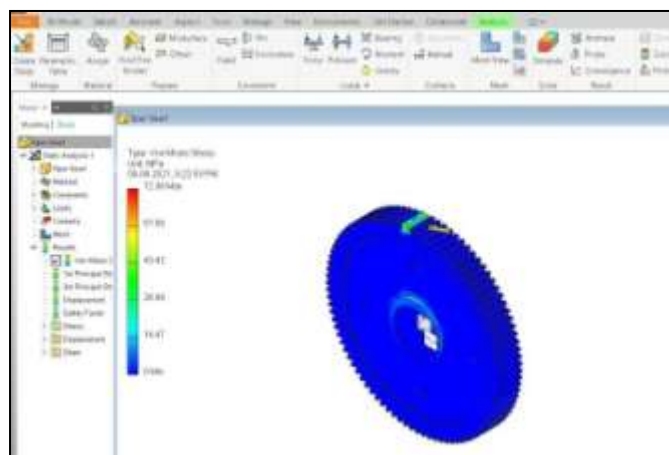


Figure 8 Stress analysis of output gear

Deformation Analysis

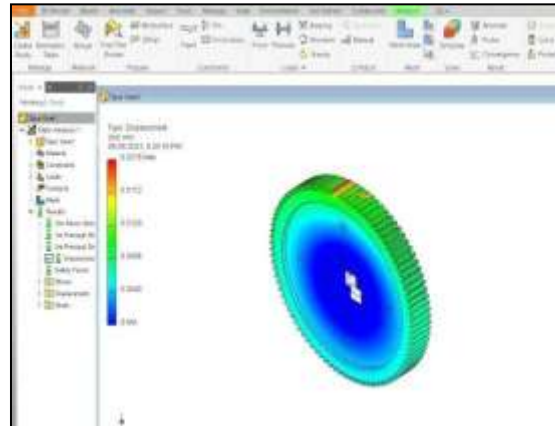


Figure 9 Deformation analysis of output gear

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