Volume No. 14, Issue No. 03, March 2025 www.ijarse.com



# Common Fixed-Point Theorems For Weakly Compatible Mapping

#### Jinam

Department of Mathematics

Baba Mastnath University, Asthal Bohar, Rohtak,

Haryana-124021, India

jinuhooda@gmail.com

### Vinod Bhatia

epartment of Mathematics

Baba Mastnath University, Asthal Bohar, Rohtak,

Haryana-124021, India

bhatiavinod88@gmail.com

### Vishvajit Singh

Department of ASH,

SAITM, F. Nagar, Gurugram, Haryana, India

Vishvajit73.sheoran@gmail.com

#### Abstract:

This paper's goal is to gather some fresh data regarding common fixed points. In this study, we define a common fixed point for pairs of weakly compatible mappings that satisfy a generalized O-weak, after first proving a point of coincidence for a pair of mappings. The main result includes a condition and contraction. Next, we demonstrate that the fixed point in the main result is unique. Finally, an application supporting our findings is provided.

Keywords: Common fixed point; point of coincidence; weakly compatible;

#### **Introduction and Preliminaries:**

The Banach Contraction Principle, sometimes referred to as the Banach fixed point theorem asserts that each fixed point on a complete metric space has a distinct contraction map. This idea is widely applied as a fundamental tool to solve problems in both the pure and applied sciences.

Volume No. 14, Issue No. 03, March 2025 www.ijarse.com



In 1969, Boyd and Wong [3] replaced the constant k in Banach contractive condition by an upper semi-continuous function as follows:

Let  $(Z^*, \Delta)$  be a complete metric space and O:  $[0, \infty) \to [0, \infty)$  be upper semi continuous from the right such that  $0 \le O(t) < t$  for all t > 0. If T:  $Z^* \to Z^*$  satisfies

$$\Delta(T(x), T(y)) \le O(\Delta(x, y))$$
 for all  $x, y \in X$ ,

then it has unique fixed-point  $x \in Z^*$  and  $\{T^n x\}$  converges to x for all  $x \in Z^*$ .

In essence, necessary requirements for the existence of fixed points are involved in fixed point theorems. Jungck [5] may have been the first to generalize Banach's contraction condition and use the idea of commutative pairs of mappings to achieve a unique fixed point. Jungck [5] first proposed the idea of compatible mappings in 1986. The concept of compatible mappings was expanded to include a broader class of mappings known as weakly compatible mappings by Jungck[5]in1996.

Alber and Guerre-Dela Briere [2] first proposed the idea of weak contraction in 1997. We now provide some fundamental definitions and findings that help support our main finding.

**Definition 1.1:** A metric space where every Cauchy sequence converges to a point in the space is called a complete metric space.

**Definition 1.2:** Two self-maps  $\eta$  and p of a metric space  $(Z, \Delta)$  are called compatible if  $\lim_{n\to\infty} \Delta(\eta \rho x_n, \rho \eta x_n) = 0$ ,

Whenever  $\{x_n\}$  is a sequence in X such that  $\lim_{n\to\infty}\eta x_n=\lim_{n\to\infty}\rho x_n=t$  for some  $t\in Z$ 

**Definition 1.3:** Two self-mappings  $\eta^*$  and  $p^*$  of a metric space  $(Z^*, \Delta)$  are said to be commuting if  $\eta^*p^*x = p^*\eta^*x$  for all  $x \in Z^*$ .

**Definition 1.4:** Two self-mapping  $\eta^*$  and  $p^*$  of a metric space  $(Z^*, \Delta)$  are called weakly compatible if they commute at their coincidence point.

**Definition 1.5:** A mapping  $\eta^*: Z^* \to Z^*$  is said to be a weak contraction if for all  $a, b \in Z^*$ , there exists a function  $O: [0, \infty) \to [0, \infty)$  with O(t) > 0 and O(o) = 0 such that

$$\Delta(\eta^*x, \eta^*y) \le \Delta(x, y) - O(\Delta(x, y))$$

Here  $(Z^*, \Delta)$  be the metric space.

In this paper we proved common fixed for four self-mapping over a given metric space.

### Volume No. 14, Issue No. 03, March 2025 www.ijarse.com



#### Main Result

Let p\* be a self – mapping on Z\* and we assume that  $(Z^*, \Delta)$  be metric space .also let b: $Z^* \times Z^* \to [0, \infty)$  is a function  $and \psi \in \Psi$ . Then we can say

- (i)  $(Z^*, \Delta)$  is an b-complete metric space;
- (ii) P\*is an b-acceptable mapping;
- (iii) P\* is a alter b-ψ- rational contraction on Z\*;
- (iv) P\*is an b-continuous mapping on Z\*;
- (v) There is  $z^* \in Z^*$  like so  $b(z^*, p^*z^*) \ge 1$ .

So p\* has a fixed point

**Theorem 1:** Let  $\eta^*$ ,  $p^*$ ,  $\psi$  and  $\lambda$  be four self-mappings on a complete metric space  $(Z^*, \Delta)$  satisfying the following conditions:

(A1) 
$$\eta^*(Z^*) \subset \lambda(Z^*), p^*(Z^*) \subset \psi(Z^*);$$

(A2) 
$$(1 + r \Delta(\psi x, \lambda x)) \Delta(\eta^* x, p^* y)^2$$

 $\leq r. \max\{\frac{1}{2} (\Delta(\Psi x, \eta x)^2 \Delta(\lambda y, p * y) + \Delta(\Psi x, \eta x) \Delta(\lambda y, p * y)), \Delta(\psi x, \eta * x) \Delta(\psi x, p * y) \Delta(\lambda y, \eta * x), \Delta(\Psi x, p * y) \Delta(\lambda y, \eta * x) \Delta(\lambda y, p * y)\} + m(\psi x, \lambda y) - O(m(\psi x, \lambda y))$ 

for all  $\eta^*$ ,  $y \in Z^*$ , were

 $m(\psi x, \lambda y) = \max \{\Delta(\psi x, \lambda y)^2, \Delta(\psi x, \eta^* x) \Delta(\lambda y, p^* y), \Delta(\psi x, p^* y) \Delta(\lambda y, \eta^* x),$ 

$$\frac{1}{2}\left[\Delta(\psi x,\,\eta^*x)\,\Delta(\psi x,\,p^*y)+\Delta(\lambda y,\,\eta^*x)\,\Delta(\lambda y,\,p^*y)\right]\},$$

 $p^* \ge 0$  is a real number and  $O: [0, \infty) \to [0, \infty)$  is a continuous function such that O(t) = 0 iff t = 0 and O(t) > 0 for all t > 0 and with the conditions (A1) and (A2) these four self-mapping of complete metric space  $(Z^*, \Delta)$  also satisfy that one of the subspaces  $\psi Z^*, \lambda Z^*, \eta^* Z^*$  and  $p^* Z^*$  be closed. Then

- (i)  $\psi$  and  $\eta^*$  have a point at coincidence;
- (ii)  $\lambda$  and p\* have a point of coincidence.

and also, if  $(\psi, \eta^*)$  and  $(\lambda, p^*)$  are weakly compatible, then  $\eta^*, p^*, \psi$  and  $\lambda$  have a unique common fixed point.

# Volume No. 14, Issue No. 03, March 2025 www.ijarse.com



**Proof:** Let  $x_0 \in Z^*$  be an arbitrary point from (A1), we can find an  $x_1$  such that  $\eta^*(x_0) = \lambda(x_1) = y_0$  and for this  $x_1$  one can find an  $x_2 \in Z^*$  such that  $P^*(x_1) = (x_2) = y_1$ 

Continuing in this way, one can construct a sequence such that

$$y_{2n} = \eta^*(x_{2n}) = \lambda(x_{2n+1}), \ y_{2n+1} = p^*(x_{2n+1}) = \psi(x_{2n+1}) \text{ for all } n \ge 0 \text{ and } \{y_n\} \text{ is a Cauchy Sequence in } Z^*.$$

Now let us assume that  $\psi Z^*$  is closed subspace of  $(Z^*, \Delta)$ . As we know that subspace of a complete metric space is complete if and only if it is closed. Hence subspace  $\psi Z^*$  is complete subspace of complete metric space  $(Z^*, \Delta)$ .

As  $\psi Z^*$  is a complete subspace of  $Z^*$ . Then there exists  $z^* \in Z^*$  such that

$$y_{2n+1} = p^*(x_{2n+1}) = \psi(x_{2n+1}) \rightarrow z^*$$

 $n \to \infty$  consequently, we can find  $w \in Z^*$  such that  $\psi w = z^*$ . Further, a Cauchy sequence  $\{y_n\}$  has a convergent subsequence  $\{y_{2n+1}\}$  and so the sequence  $\{y_n\}$  converges and hence a subsequence  $\{y_{2n}\}$  also converges. Thus, we have

$$y_{2n+1} = \eta^*(x_{2n}) = \lambda(x_{2n+1}) \to z^* \text{ as } n \to \infty.$$

Letting x = w and  $y = z^*$  in (A2), we get

$$\left[1 + r\Delta(\psi w, \lambda z^*)\right] \Delta(\eta^* w, p^* z^*)^2 \leq r \; max \; \left\{\frac{1}{2} \; \left[\Delta(\psi w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*, p^* z^*)) + \Delta(\psi(w, \eta^* w)^2 \; \Delta(\lambda z^*)) +$$

$$\Delta(\lambda z^*, p^*z^*)^2],$$

$$\Delta(\psi w, \eta^* w) \Delta(\psi w, p^* z^*) \Delta(\lambda z^*, \eta^* w), \Delta(\psi w, p^* z^*) \Delta(\lambda z^*, \eta^* w) \Delta(\lambda z^*, p^* z)$$
+ m (\psi w, \lambda z^\*) - O (m (\psi w, \lambda z^\*)),

where

$$m(\psi w, \lambda z^*) = \max \{\Delta(\psi w, \lambda z^*)^2, \Delta(\psi w, \eta^* w) \Delta(\lambda z^*, p^* z^*), \Delta(\psi w, p^* z^*) \Delta(\lambda z^*, \eta^* w), \Delta(\lambda$$

$$\frac{1}{2}\left[\Delta(\psi w,\,\eta^*w)\Delta(\psi w,\,p^*z^*) + \Delta(\lambda z^*,\,\eta^*w)\,\Delta(\lambda z^*,\,p^*z^*)\right]\}.$$

Since

$$\begin{split} M\left(\psi w, \lambda z^{*}\right) &= \max \; \left\{ \Delta(z^{*}, \, z^{*})^{2}, \, \Delta(z^{*}, \, \eta^{*}w) \; \Delta(p^{*}z^{*}, \, p^{*}z^{*}), \, \Delta(z^{*}, \, z^{*}) \; \Delta(z^{*}, \, \eta^{*}w), \right. \\ &\left. \frac{1}{2} \left[ \Delta(z^{*}, \, \eta^{*}w) \; \Delta(z^{*}, \, z^{*}) + \Delta(z^{*}, \, \eta^{*}w) \; \Delta(p^{*}z^{*}, \, p^{*}z^{*}) \right] \right\} = 0, \end{split}$$

[As  $\Delta(x, x) = 0$  according to the definition of metric space]

# Volume No. 14, Issue No. 03, March 2025 www.ijarse.com



$$\left[1 + r\Delta(z^*,\,z^*)\right] \Delta(\eta^*w,\,z^*)^2 \leq r \,\, \text{max} \,\, \{\frac{1}{2} \left[\Delta(z^*,\,\eta^*w)^2 \,\Delta(z^*,\,z^*) + \Delta(z^*,\,\eta^*w) \,\, \Delta(z^*,\,z^*)^2\right],$$

$$\Delta(z^*, \eta^*w) \Delta(z^*, z^*) \Delta(z^*, \eta^*w), \Delta(z^*, z^*) \Delta(z^*, \eta^*w) \Delta(z^*, z^*) + \phi(0).$$

This implies that  $\eta^*w=z^*$  and so  $\eta^*w=\psi w=z^*$ . Therefore, w is a coincidence point of  $\psi$  and  $\eta^*$ .

Since  $z *= \eta * w \in \eta * Z * \subset \lambda Z *$ , there exists  $v \in Z *$  such that  $z * = \lambda v$ .

Now we claim that  $p^*v = z^*$ . Letting as  $x = x_{2n}$  and y = v in (A2) we get

$$[1 + r\Delta(\psi x_{2n}, \eta^* \lambda v)]\Delta(\eta^* x_{2n}, p^* v)^2$$

$$\leq r \; max \; \{ \frac{1}{2} \left[ \Delta(\psi x_{2n}, \, \eta^* x_{2n})^2 \; \Delta(\lambda v, \, p^* v) + \Delta(\psi x_{2n}, \, \eta^* x_{2n}) \; \Delta(\lambda v, \, p^* v)^2 \right],$$

$$\Delta(\psi \; x_{2n}, \, \eta^* \; x_{2n}) \; \Delta(\psi \; x_{2n}, \, p^*v) \Delta(\lambda z^*, \, \eta^* x_{2n}), \; \Delta(\psi x_{2n}, \, p^*v) \; \Delta(\lambda v, \, \eta^* x_{2n}) \; \Delta(\lambda v, \, p^*v) \}$$

$$+m (\psi x_{2n}, \lambda v) - O (m (\psi x_{2n}, \lambda v)),$$

where

$$m(\psi x_{2n}, \lambda v) = \max \{\Delta(\psi x_{2n}, \lambda v)^2, \Delta(\psi x_{2n}, \eta^* x_{2n}) \Delta(\lambda v, p^* v), \Delta(\psi x_{2n}, p^* v) \Delta(\lambda v, \eta^* x_{2n}), \Delta(\lambda$$

$$\frac{1}{2} \left[ \Delta(\psi x_{2n},\, \eta \ *x_{2n}) \ \Delta(\psi \ x_{2n},\, p *v) + (\lambda v,\, \eta * \ x_{2n}) \ \Delta(\lambda v,\, p *v) \right] \} = 0.$$

Therefore,

$$[1 + r\Delta(z^*, z^*)] \Delta(z^*, p^*v)^2 \le r \max\{1/2[0+0], 0, 0\} + 0 - O(0).$$

This gives 
$$z^* = p^*v$$
 and hence  $z^* = p^*v = \lambda v$ .

Therefore, v is a coincidence point of  $\lambda$  and  $p^*$ .

Since 
$$\eta^*z^* = \eta^*(\psi w) = \psi(\eta^*w) = \psi z^*$$
,

$$P*_Z *= p*(\lambda v) = \lambda(p*v) = \lambda z*.$$

Now, we show that  $\eta^*z^* = z^*$ , for this, letting  $x = z^*$  and  $y = x_{2n+1}$  in (A2), we get

$$[1 + r\Delta(\psi z^*, \lambda \ x_{2n+1})]\Delta(\eta^*z^*, p^*x_{2n+1})^2$$

$$\leq r \max \big\{ \frac{1}{2} \big[ \Delta(\psi z^*, \, \eta^* z^*)^2 \, \Delta(z^*, \, z^*) + \Delta(\psi z^*, \, \eta^* z^*) \, \Delta(z^*, \, z^*)^2 \big],$$

$$\Delta(\psi z^*, \eta^* z^*) \, \Delta(\psi z^*, z^*) \, \Delta(z^*, \eta^* z^*), \, \Delta(\psi z^*, z^*) \, \Delta(z^*, \eta^* z^*) \, \Delta(z^*, z^*)] \}$$

$$+m (\psi z^*, z^*) - O (m (\psi z^*, z^*)),$$

where

$$m\;(\psi z^*,\,z^*) = max\;\{\psi z^*,\,z^*)^2,\,\Delta(\psi z^*,\,\eta^*z^*)\;\Delta(z^*,\,z^*),\,\Delta(\psi z^*,\,z^*)\;\Delta(z^*,\,\eta^*z^*),$$

# Volume No. 14, Issue No. 03, March 2025 www.ijarse.com



$$\begin{split} &\frac{1}{2} \left[ \Delta(\psi z^*, \, \eta^* z^*) \, \Delta(\psi z^*, \, z^*) + \Delta(z^*, \, \eta^* z^*) \, \Delta(z^*, \, z^*) \right] \} \\ &= \Delta(\eta^* z^*, \, z^*)^2 \end{split}$$

Therefore, we have

$$\left[1+r\Delta(\eta^*z^*,\,z^*)\right]\Delta(\eta^*z^*,\,z^*)^2 \leq r\,\max\,\big\{\frac{1}{2}\,[0+0],\,0,\,0\big\} + \Delta(\eta^*z^*,\,z^*)^2 - O\,(\Delta(\eta^*z^*,\,z^*)^2).$$

Thus, we get  $\Delta(\eta^*z^*, z^*)^2 = 0$ . This implies that  $\eta^*z^* = z^*$ . Hence  $\eta^*z^* = \psi z^* = z^*$ .

Next, we claim that p\*z \*= z\*. Now letting  $x = x_{2n}$  and y = z\* in (A2) we get

$$[1 + r\Delta(\psi x_{2n}, \lambda z^*)] \Delta(\eta *x_{2n}, p^*z^*)^2$$

$$\leq r \; max \; \{ \frac{1}{2} \left[ \Delta(\psi \; x_{2n}, \, n \; x_{2n})^2 \; \Delta(\lambda z^*, \, p^*z^*) + \Delta(\psi \; x_{2n}, \, \eta^* \; x_{2n}) \; \Delta(\lambda z^*, \, p^*z^*)^2 \right],$$

$$\Delta(\psi \ x_{2n}, \ \eta^* \ x_{2n}) \ \Delta(\psi \ x_{2n}, \ p^*z^*) \ \Delta(\lambda z^*, \ \eta^* \ x_{2n}), \ \Delta(\psi \ x_{2n}, \ p^*z^*) \ \Delta(\lambda z^*, \ \eta \ ^*x_{2n}), \ \Delta(\lambda z^*, \ \eta^* x_{2n}), \ \Delta(\lambda z$$

where

$$\begin{split} m(\psi x_{2n}, \lambda z^*) &= max \{ \Delta(\psi \; x_{2n}, \lambda z^*)^2, \, \Delta(\psi \; x_{2n}, \, \eta^* \; x_{2n}) \; \Delta(\lambda z^*, \, p^*z^*), \, \Delta(\psi \; x_{2n}, \, p^*z^*) \; \Delta(\lambda z^*, \, \eta^* \; x_{2n}), \\ \frac{1}{2} \left[ \Delta(\psi \; x_{2n}, \, \eta^* \; x_{2n}) \; \Delta(\psi \; x_{2n}, \, p^*z^*) + \Delta(\lambda z^*, \, \eta^* \; x_{2n}) \; \Delta(\lambda z^*, \, p^*z^*) \right] \} \\ &= \Delta(z^*, \, p^*z^*)^2. \end{split}$$

Hence, we get

$$[1 + r \Delta(z^*, p^*z^*)] \Delta(z^*, p^*z^*)^2 \le r. \max \left\{ \frac{1}{2} [0 + 0], 0, 0 \right\} + \Delta(z^*, p^*z^*)^2 - O(\Delta(z^*, p^*z^*)^2).$$

gives  $z^* = p^*z^*$  and so  $z^* = p^*z^* = \lambda z^*$ . Therefore,  $z^*$  is a common fixed point of  $\eta^*$ ,  $p^*$ ,  $\psi$  and  $\lambda$ .

Similarly, we can complete the proofs for the cases that subspaces  $\lambda Z^*$  or  $\eta^*Z^*$  or  $p^*Z^*$  is closed.

Now, we have to prove the uniqueness. Suppose  $z^*$  and w are two common fixed points of  $\eta^*$ ,  $p^*$ ,  $\psi$  and  $\lambda$  with  $z^*$  and w are distinct. Letting  $x=z^*$  and y=w. We get

$$[1+r \Delta(\psi z^*, \eta^* w)] \Delta(\eta^* z, p^* w)^2$$

$$\leq r. \max \left\{ \frac{1}{2} \left( \Delta(\psi z^*, \eta^* z^*)^2 \Delta(\lambda w, p^* w) + \Delta(\psi z^*, \eta^* z) \Delta(\lambda w, p^* w)^2, \right. \right.$$

# Volume No. 14, Issue No. 03, March 2025 www.ijarse.com



$$\begin{split} & \Delta(\psi z^*, \eta^* z^*) \, \Delta(\psi z^*, p^* z^*) \, \Delta(\lambda w, \eta^* z^*), \\ & \Delta(\psi z^*, p^* w) \, \Delta(\lambda w, \eta^* z^*) \, \Delta(\lambda w, p^* w) \} \\ & + m \, (\psi z^*, \lambda w) - O \, (m \, (\psi z^*, \lambda w)) \\ & m \, (\psi z^*, \lambda w) = max \, \left\{ \Delta(\psi z^*, \lambda w)^2, \, \Delta(\psi z^*, \eta^* z^*) \, \Delta(\lambda w, p^* w), \, \Delta(\psi z^*, p^* w) \, \Delta(\lambda w, \eta^* z^*), \right. \\ & \left. \frac{1}{2} \left[ \Delta(\psi z, \eta^* z^*) \, \Delta(\psi z^*, p^* w) + \Delta(\lambda w, \eta^* z^*) \, \Delta(\lambda w, p^* w) \right] \right\} \\ & = 0 \end{split}$$

So

$$[1 + r \Delta(\psi z^*, \eta^* w)] \Delta (\eta^* z^*, p^* w)^2$$

$$\leq r. \max \{0, 0, 0\} + m (\psi z^*, \lambda w) - O (m (\psi z^*, \lambda w))$$

$$= r. \max \{0, 0, 0\} + 0 - O (0)$$

$$= r \times 0 + 0 - 0$$

$$= 0$$

$$[1 + r \Delta(\psi z^*, \eta^* w)] \Delta(\eta^* z, p^* w)^2 \le 0$$

which implies that

$$\Delta(\eta^*z^*, p^*w)^2 = 0.$$

as  $z^*$  and w are fixed point so

$$\eta^*z^* = z^* \qquad \qquad p^*w = w$$

$$\Delta(z^*, w)^2 = 0$$

Hence 
$$z^* = w$$

This proves the uniqueness of the fixed point.

Hence proved.

**Example:** Let Z = [2, 18] and  $\Delta$  be a usual metric. Define self-mapping  $\eta$ ,  $\rho$ , $\psi$  and  $\lambda$  on Z by

$$\eta x = \begin{cases} 2 & \text{if} & x = 2 \\ 12 & \text{if} & 2 < x \le 5 \\ x - 3 & \text{if} & x > 5 \end{cases} \qquad \rho x = \begin{cases} 2 & \text{if} & x = 2 \\ 6 & \text{if} & x > 2 \end{cases}$$

$$\psi x = \begin{cases} 2 & \text{if} & x = 2 \\ 6 & \text{if} & 2 < x \le 5 \\ 2 & \text{if} & x > 5 \end{cases} \qquad \lambda x = \begin{cases} x & \text{if} & x = 2 \\ 3 & \text{if} & x > 2 \end{cases}$$

# International Journal of Advance Research in Science and Engineering Volume No. 14, Issue No. 03, March 2025

www.ijarse.com

IJARSE ISSN 2319 - 8354

Let us consider a sequence  $\{y_n\}$  with  $y_n = 2$ . As we find that all the conditions of the main result are satisfied. So, this theorem is applicable in this example and hence 2 is the unique common fixed point of  $\eta$ , p,  $\psi$  and  $\lambda$ .

#### **Conclusion:**

We proved a common fixed-point theorem for pairs of weakly compatible mappings satisfying a generalized O-weak contraction condition and also a different distance condition of metric function. And also, we have given an example in support of our result.

### References

- 1. Y. I. Alber and S. Guerre-Delabriere, "Principle of weakly contractive maps in Hilbert spaces." *New Results Operator Theory Adv. Appl.*, vol. 98, no. 1, pp. 7-22, 1997, doi: 10.1137/050641867.
- 2. B. Boonsri and S. Saejung, "Fixed point theorems for contractions of Reich type on a metric space with a graph," *J. Fixed Point Theory Appl.*, vol. 20, no. 2, pp. 1-17, 2018, doi: 10.1007/s11784-018-0565-y.
- 3. D. W. Boyd and J. S. W. Wong, "On nonlinear contractions," *Proc. Am. Maths. Soc.*, vol. 20, no. 2, pp. 458-464, 1969.
- 4. D. Jain, S. Kumar, S. Kang. And C. Jung, "Weak contraction condition for compatible mappings involving cubic terms of the metric function," *Far Esat J. Math. Sci.*, vol. 103, no. 4, pp. 799-818, 2018, doi: 10.17654/MS103040799.
- 5. G. Jungck, "Commuting mappings and fixed points," *Am. Math. Monthly*, vol. 83, pp. 261-263, 1976.
- 6. G. Jungck and B.E. Rhoades, "Fixed points for set valued functions without continuity," *Indian J. Pure Appl. Math.*, vol. 29, no. 3, pp. 227-238, 1998.
- 7. S. Kajanto and A. Lukacs, "On the conditions of fixed-point theorems concerning F-contractions," *Results Math.*, vol. 73, no. 2, pp. 1-10, 2018, doi: 10.1007/s00025-018-0846-1.
- 8. K. Kim, "Convergence and stability of generalized φ-weak contraction mapping in CAT (0) spaces," *Open Math.*, vol. 15, no. 1, pp. 1063-1074, 2017, doi: 10.1515/math-2017-00089.

Volume No. 14, Issue No. 03, March 2025 www.ijarse.com



- 9. S. Kumar and S. K. Garg, "Expansion mapping theorems in metric spaces," *Int. J. Contemp. Math. Sci.*, vol. 4, no. 36, pp. 1749-1758, 2009.
- 10. H. K. Pathak, Y. Cho, and S. Kang, "Remarks on R-weakly commuting mappings and common fixed-point theorems, "*Bull. Korean Math. Soc.*, vol. 34, no. 2, pp. 247-257, 1997.
- 11. B.E. Rhoades, "Some theorems on weakly contractive maps. Proceedings of the Third World Congress of Nonlinear Analysis, Part 4 (Catania, 2000)," *Nolinear Anal.*, vol. 47, no. 4, pp. 2683-2693, 2001, doi: /10.1016/S0362-546X (01)00388-1.
- 12. S. Sessa, "On a weak commutativity condition of mappings in fixed point consideration," *Publ. Inst. Math. (Beograd)*, vol. 32, pp. 146-153, 1982.