



A Survey on Classification of Remote Sensing Data using Machine Learning Algorithms

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ABSTRACT

Due to elevated number of spectral channels and large information of size, classification of Remote sensing data are difficult to be processed and classified with high accuracy and less computational time. In general, large quantity of data collected from the GIS namely satellite, aerial sensors, and telescope. Numerous classification techniques have been designed for the analysis of Remote sensing data. In this context, analyzing the best classification algorithm is big issue in Image processing field. In this literature survey, summarize the advanced techniques which are based on Clustering and SVM. Moreover we have provided the guidelines to future researchers to enhance further algorithmic developments in Remote sensing applications.

Keywords: Remote sensing Data, Clustering, SVM.

I.INTRODUCTION

Remote sensing is the techniques which provide the modern information about an area such as Land cover classification, climate, minerals, vegetation, marine resources, urban monitoring, forestry, disaster management, robot navigation and many others with the help of sensors but without having any direct contact with the objects. When we classifying the remote sensing data, the necessary algorithm were implemented to carry out the interpretation and analysis of Electromagnetic spectrum. The major steps of image classification involve image preprocessing, detection and extraction of object, feature extraction, selection of training samples, algorithms and accuracy assessment. For remotely sensed scene analysis, images of the earth's surface are captured by sensors in remote sensing satellites or by a multi-Spectra) scanner housed in an aircraft and then transmitted to the Earth Station for further processing [3, 4]. In this paper we have summarized some of the traditional algorithms which are based on SVM and Clustering. Clustering is the process of organizing the objects into groups. Support vector machine is a nonparametric statistical method for



addressing supervised classifications and regression problems. In SVM, kernel functions that accurately reflect the similarity among the samples and also satisfy the Mercer's condition are linear kernel, polynomial kernel, radial basis function kernel and sigmoid kernel. The rest of the paper organized as follows. Section 2 describes the overview and analysis of Clustering, section 3 deals with the classification model based on SVM. Section 4 illustrates the performance measures of Remote sensing data finally section 5 concludes the article.

II.CLUSTERING

Clustering is the process of organizing the objects into groups. In generally is classification methodology is carried out of some the characteristics such as Data collection, Initial screening, representation, clustering tendency, cluster strategy, validation and interpretation. Based on above characteristics classification is carried out two aspects such as supervised classification and unsupervised classification. Clustering has become a widely studied problem in a variety of application domains, such as in data mining and knowledge discovery [1], [2] statistical data analysis [3], [4] data classification and compression [6], medical image processing [5] and bioinformatics [6]. Several algorithms have been proposed in the literature for clustering [7], [8]. A. L. Abul is explained about Cluster Validity Analysis Using Sub sampling [10]. The objective of all clustering algorithms is to divide a set of data points into subsets so that the objects within a subset are similar to each other and objects that are in different subsets have diverse qualities [11], [12], [13]. Bradley and Fayyad have proposed an algorithm for refining the initial cluster centers. Not only are the true clusters found more often, but the clustering algorithm also iterates fewer times. Some clustering 176 methods improve performance by reducing the distance calculations. For example, Judd et al. proposed a parallel clustering algorithm P-CLUSTER which uses three pruning techniques. Ming-Chuan Hung, explained about an Efficient k-Means Clustering Algorithm Using Simple Partitioning based on Remote sensing data. The Table1 describes the analysis of clustering Algorithms.

Table 1 : Clustering Algorithms

Algorithms	RS Data	References
K-Means Clustering	Multispectral, Hyper spectral	[2]
Fuzzy C-Means	Multispectral, Hyper spectral	[4]
Fast and Exact K-means	Multispectral, Hyper spectral	[8]
K-Means based mixture model	Multispectral, Hyper spectral	[5]
Boosting	Multispectral,	[34]



Clustering	Hyper spectral	
Affinity propagation	Multispectral, Hyper spectral	[15]
StrAP	Multispectral, Hyper spectral	[18]
Median Fuzzy C-Means	Multispectral, Hyper spectral	[33]
Fuzzy AP	Multispectral, Hyper spectral	[40]
ED Algorithm	Multispectral, Hyper spectral	[31]
MD Algorithm	Multispectral, Hyper spectral	[56]
CD Algorithm	Multispectral, Hyper spectral	[21]
Fuzzy possibilistic	Multispectral, Hyper spectral	[4]
Modify Fuzzy possibilistic	Multispectral, Hyper spectral	[56]
Kernel Fuzzy possibilistic	Multispectral, Hyper spectral	[25]
Modify kernel fuzzy possibilistic	Multispectral, Hyper spectral	[23]

IV.SUPPORT VECTOR MACHINE

SVMs are nonparametric statistical approaches for addressing supervised classification and regression problems. In this context, SVM determine a hyper plane that discriminates data set into set of classes for classifying the remote sensing data. The SVM approach has been applied first to the classification of hyper spectral data without reducing the dimensionality. In this survey, we have focus on SVM-based approaches, including active SVMs, S^3 Vs, and composite SVMs methods for addressing the remote sensing problem. In this article we have analyzed the following machine learning methods.

a. Active Machine Learning



- b. Semi supervised SVMs
- c. SVMs integrated with other approaches

The table 2 describes machine learning methods based Algorithm for classifying different kinds of RS Data.

Algorithms	RS Data	References
Active SVM	Multispectral	[55]
Adaptive kernel	Hyperspectral	[56]
Bootstrapped SVM	Multispectral	[57]
Batch mode active SVM	MODIS	[60]
TSVM	Hyperspectral	[75]
RVM	Hyperspectral	[78]
P-SVM	Hyperspectral	[80]
Primal SVM	Multispectral	[67]
LapSVM	Hyperspectral	[87]
S ³ VM	Multispectral	[99]
Cluster based SVM	Hyperspectral	[100]
GA and SVM	Hyperspectral	[95]
FCM and SVM	Multispectral	[90]
PSO and SVM	Hyperspectral	[98]
Fuzzy clustering and SVM	Hyperspectral & multispectral images	[90]

V.PERFORMANCE MEASURES

A. MEAN SQUARE ERROR

MSE measures the average of the square “error” between the five remote sensing images. The error is the amount by which the estimator differs from the quantity to be estimated. The difference occurs because of randomness or



because the estimator doesn't account for information that could produce a more accurate estimate. The formula for mean square is given as

$$MSE = \left[\frac{1}{MN} \sum_{i=0}^{M-1} \sum_{j=0}^{N-1} [\hat{f}(i,j) - f(i,j)]^2 \right]^{1/2}$$

Where $M*N$ is the size of the image, $\hat{f}(i, j)$ and $f(i, j)$ are the matrix element of the fused and the original image at (i, j) pixel. To compare the performance, an objective image quality assessment, Mean Square Error (MSE) results of remote sensing images are shown in Table.

B. PEAK SIGNAL TO NOISE RATIO (PSNR)

PSNR for remote sensing images are calculated by using fusion Techniques.

$$PSNR = 10 \log_{10} \left[\frac{M \times N}{RMSE} \right]$$

Here remote sensing is original image and noise in error is fused image. In general, a good fused image is one with low MSE and high PSNR [26]. That means that the image has low error. To compare the performance, an objective image quality assessment, Peak Signal-to-Noise Ratio (PSNR) results of five remote sensing images are shown in Table.

C. NORMALIZED CROSS CORRELATION

NCC in which the brightness of the image and template can vary due to lighting and exposure conditions, the images can be first normalized. This is typically done at every step by subtracting the mean and dividing by the standard deviation. That is the cross correlation of the template, $t(x, y)$ with sub image $f(x, y)$ is

$$NCC = \frac{1}{n} \sum_{x,y} \frac{(f(x,y) - \bar{f})(t(x,y) - \bar{t})}{\sigma_f \sigma_t}$$

Where n is the number of pixels in $t(x, y)$ and $f(x, y)$, $\bar{f}$ is the average of f and σ_f is standard deviation of f . In functional analysis terms, can be thought of as the dot product of two normalized vectors, that is if $F(x, y) = f(x, y) - \bar{f}$ and $T(x, y) = t(x, y) - \bar{t}$ Then the above sum is equal to F and T is real matrices of Normalized Cross Correlation.

D. AVERAGE DIFFERENCE

The average number of a set is the total of those numbers divided by the number of items in that set and the average brightness of a region is defined as the sample mean of the pixel brightness within that region. The



difference in visual properties that makes an object distinguishable from other objects. The formula for average difference is given as

$$AD = \sum_{j=1}^M \sum_{k=1}^N (x_{j,k} - x'_{j,k}) / M N$$

E. MAXIMUM DIFFERENCE

As expected the metrics that are responsive to distortions are also almost always responsive to the image set. Conversely, the metrics that do not respond to variation of the image set are also not very discriminating with respect to distortion types. The fact that the metrics are sensitive, as would be expected, to both the image content and distortion artifacts does not eclipse their potential as quality metrics.

F. NORMALIZED ABSOLUTE ERROR

Normalization is the process of isolating statistical error in repeated measured data. Absolute error is the uncertainty in a measurement, which is expressed using the relevant units. Also, absolute error may be used to express the inaccuracy in a measurement. Normalized absolute error formula is given as.

$$NAE = \frac{\sum_{j=1}^M \sum_{k=1}^N |x_{j,k} - x'_{j,k}|}{\sum_{j=1}^M \sum_{k=1}^N |x_{j,k}|}$$

G. KAPPA ANALYSIS

Kappa coefficients are widely used as classification accuracy assessment for remote sensed data, the result of performing Kappa Analysis is a KHAT statistic (an estimate of Kappa), which are computed as

$$\hat{K} = \frac{N \sum_{i=1}^r x_{ii} - \sum_{i=1}^r (x_{i+} \cdot x_{+i})}{N^2 - \sum_{i=1}^r (x_{i+} \cdot x_{+i})}$$

Where r is the number of rows in the error matrix (also called the confusion matrix), x_{ii} is the number of observations in row i and column i , x_{i+} and x_{+i} are the marginal totals of row i and column i , respectively, and N is the total number of observations.

VI.CONCLUSION

In this review article, we have provided a quick reference of the compendium of recently developed SVM-based techniques in RS applications. We also pointed out traditional methods used for image classification. Most of the findings indicate that there is sufficient empirical evidence to support the adoption of these processing algorithms.



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