



AMMENSALISM WITH MORTAL ENEMY SPECIES- A SERIES SOLUTION

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ABSTRACT

The paper deals to compute a series solution in an Ammensal Model. The Ammensal species has un limited resources with mortal enemy species. The model equations are made by a pair of non linear first order differential equations. Homotopy perturbation method is used for finding series solution.

Keywords: Ammensalism, Homotopy Analysis, Stability, Dominance Reversal Time

I. INTRODUCTION

Homotopy perturbation method is a better tool to derive a series solution for non linear differential equations. Abbasbandy,S [1] did constructive study in the concept of asymptotic techniques .Later Liao[5-8] suggested many ideas and developed Homotopy Perturbation Method (HPM) in 1992. Few other effective and efficient methods were developed by many Mathematicians [2,4].In the past two decades, the HPM concept has been utilized in some applications of Engineering and Sciences[3,9].

II. BASIC IDEA OF HOMOTOPY PERTURBATION METHOD

Step (1): Let us consider nonlinear differential equation:

$$A(u) - f(r) = 0, \quad r \in \Omega \quad (I)$$

With the boundary condition

$$B\left(u, \frac{\partial u}{\partial n}\right) = 0, \quad r \in \Gamma$$

Where A is a general differential operator, B a boundary operator, $f(r)$ is a known analytic function, Γ is the boundary of the domain Ω and $\frac{\partial}{\partial n}$ denotes differentiation among the normal drawn outwards from Ω .

Step (2): In general the operator A , is divided into two parts: a linear part L and a nonlinear part N . Therefore above differential equation(I) is expressed in the form of

$$L(u) - N(u) - f(r) = 0 \quad (II)$$

Step (3):

With the help of Homotopy Perturbation Method (HPM), one can constitute a homotopy $v(r, p): \Omega \times [0, 1] \rightarrow R$ which satisfies



$$H(v, p) = (1-p)[L(v) - L(u_0)] + p[A(v) - f(r)] = 0, \quad p \in [0, 1], r \in \Omega \quad (\text{III})$$

It is nothing but

$$H(v, p) = L(v) - L(u_0) + pL(u_0) + p[A(v) - f(r)] = 0 \quad (\text{IV})$$

Where $p \in [0, 1]$ is named as an embedding parameter, and u_0 is an initial approximation of equation (1), which satisfies the boundary conditions.

Step (4): Then equations (III), (IV) follow that

$$H(v, 0) = L(v) - L(u_0) = 0$$

$$\text{And } H(v, 1) = A(v) - f(r) = 0$$

Thus the changing process of p from zero to unity is just that of $v(r, p)$ from $u_0(r)$ to $u(r)$.

Step (5): According to the HPM, we can first use the imbedding parameter p as a 'small parameter' and assume that the solutions of the equations (III) and (IV) can be written as a power series in p :

$$v = v_0 + pv_1 + p^2v_2 + p^3v_3 + p^4v_4 + \dots$$

The approximate solution of equation (I) can be obtained as

$$u = \lim_{p \rightarrow 1} v = v_0 + v_1 + v_2 + v_3 + v_4 + \dots$$

III. NOTATIONS ADOPTED

$N_1(t)$: The population rate of the species S_1 at time t

$N_2(t)$: The population rate of the species S_2 at time t

a_i : The natural growth rate of S_i , $i = 1, 2$.

a_{ii} : The rate of decrease of S_i due to its own insufficient resources, $i = 1, 2$.

a_{12} : The inhibition coefficient of S_1 due to S_2 i.e The Commensal coefficient.

The state variables N_1 and N_2 as well as the model parameters $a_1, a_2, a_{11}, a_{22}, K_1, K_2, \alpha, h_1, h_2$ are assumed to be non-negative constants.

IV. BASIC EQUATIONS

$$\frac{dN_1}{dt} = a_1N_1 - a_{11}N_1^2 - a_{12}N_1N_2 \quad (1)$$

$$\frac{dN_2}{dt} = -a_2N_2 \quad \text{With initial conditions } N_1(0) = c_1 \text{ and } N_2(0) = c_2 \quad (2)$$

The following system can be constructed by the concept of homotopy as follows

$$v_1' - N_{10}' + p(N_{10}' - a_1v_1 + a_{11}v_1^2 - a_{12}v_1v_2) = 0 \quad (3)$$

$$v_2' - N_{20}' + p(N_{20}' + a_2v_2) = 0 \quad (4)$$



$$v_{1,0}(t) = N_{10}(t) = v_1(0) = c_1 \quad (5)$$

$$v_{2,0}(t) = N_{20}(t) = v_2(0) = c_2 \quad (6)$$

$$\text{and } v_1(t) = v_{1,0}(t) + pv_{1,1}(t) + p^2v_{1,2}(t) + p^3v_{1,3}(t) + p^4v_{1,4}(t) + p^5v_{1,5}(t) + \dots \quad (7)$$

$$v_2(t) = v_{2,0}(t) + pv_{2,1}(t) + p^2v_{2,2}(t) + p^3v_{2,3}(t) + p^4v_{2,4}(t) + p^5v_{2,5}(t) + \dots \quad (8)$$

Where $v_{i,j}(i = 1,2, j = 1,2,3 \dots)$ are to be computed by substituting (5), (6), (7), (8) in (3), (4)

We get

$$\begin{aligned} &v'_{1,0}(t) + pv'_{1,1}(t) + p^2v'_{1,2}(t) + p^3v'_{1,3}(t) + p^4v'_{1,4}(t) + p^5v'_{1,5}(t) + \dots - N'_{10} + \\ &p[N'_{10} - a_1(v_{1,0}(t) + pv_{1,1}(t) + p^2v_{1,2}(t) + p^3v_{1,3}(t) + p^4v_{1,4}(t) + p^5v_{1,5}(t) + \dots) \\ &+ a_{11}(v_{1,0}(t) + pv_{1,1}(t) + p^2v_{1,2}(t) + p^3v_{1,3}(t) + p^4v_{1,4}(t) + p^5v_{1,5}(t) + \dots)(v_{1,0}(t) + pv_{1,1}(t) \\ &+ p^2v_{1,2}(t) + p^3v_{1,3}(t) + p^4v_{1,4}(t) + p^5v_{1,5}(t) + \dots) + a_{12}(v_{1,0}(t) + pv_{1,1}(t) + p^2v_{1,2}(t) + p^3v_{1,3} \\ &(t) + p^4v_{1,4}(t) + p^5v_{1,5}(t) + \dots)(v_{2,0}(t) + pv_{2,1}(t) + p^2v_{2,2}(t) + p^3v_{2,3}(t) + p^4v_{2,4}(t) + \\ &p^5v_{2,5}(t) + \dots)] = 0 \end{aligned} \quad (9)$$

From equation (4)

$$\begin{aligned} &v'_{2,0}(t) + pv'_{2,1}(t) + p^2v'_{2,2}(t) + p^3v'_{2,3}(t) + p^4v'_{2,4}(t) + p^5v'_{2,5}(t) + \dots - N'_{20} \\ &+ p[N'_{20} + a_2(v_{2,0}(t) + pv_{2,1}(t) + p^2v_{2,2}(t) + p^3v_{2,3}(t) + p^4v_{2,4}(t) + p^5v_{2,5}(t) + \dots) \\ &(v_{2,0}(t) + pv_{2,1}(t) + p^2v_{2,2}(t) + p^3v_{2,3}(t) + p^4v_{2,4}(t) + p^5v_{2,5}(t) + \dots)] = 0 \end{aligned} \quad (10)$$

From (9),

$$\begin{aligned} &0 + pv'_{1,1}(t) + p^2v'_{1,2}(t) + p^3v'_{1,3}(t) + p^4v'_{1,4}(t) + p^5v'_{1,5}(t) + \dots - 0 \\ &+ p[0 - a_1v_{1,0}(t) - a_1pv_{1,1}(t) - a_1p^2v_{1,2}(t) - a_1p^3v_{1,3}(t) - a_1p^4v_{1,4}(t) - a_1p^5v_{1,5}(t) - \dots \\ &+ a_{11}v_{1,0}^2(t) + a_{11}pv_{1,0}(t)v_{1,1}(t) + a_{11}p^2v_{1,0}(t)v_{1,2}(t) + a_{11}p^3v_{1,0}(t)v_{1,3}(t) \\ &+ a_{11}p^4v_{1,0}(t)v_{1,4}(t) + \dots + a_{11}pv_{1,0}(t)v_{1,1}(t) + a_{11}p^2v_{1,1}^2(t) + a_{11}p^3v_{1,1}(t)v_{1,2}(t) \\ &+ a_{11}p^4v_{1,1}(t)v_{1,3}(t) + a_{11}p^5v_{1,1}(t)v_{1,4}(t) + \dots + a_{11}p^2v_{1,0}(t)v_{1,2}(t) + a_{11}p^3v_{1,1}(t)v_{1,2}(t) \\ &+ a_{11}p^4v_{1,2}^2(t) + a_{11}p^5v_{1,2}(t)v_{1,3}(t) + \dots + a_{11}p^3v_{1,0}(t)v_{1,3}(t) + a_{11}p^4v_{1,1}(t)v_{1,3}(t) \\ &+ a_{11}p^5v_{1,2}(t)v_{1,3}(t) + \dots + a_{11}p^4v_{1,0}(t)v_{1,4}(t) + a_{11}p^5v_{1,1}(t)v_{1,4}(t) + \dots \\ &+ a_{11}p^5v_{1,0}(t)v_{1,5}(t) + \dots + a_{12}v_{1,0}(t)v_{2,0}(t) + a_{12}pv_{1,0}(t)v_{2,1}(t) + a_{12}p^2v_{1,0}(t)v_{2,2}(t) \\ &+ a_{12}p^3v_{1,0}(t)v_{2,3}(t) + a_{12}p^4v_{1,0}(t)v_{2,4}(t) + \dots + a_{12}pv_{1,1}(t)v_{2,0}(t) + a_{12}p^2v_{1,1}(t)v_{2,1}(t) \\ &+ a_{12}p^3v_{1,1}(t)v_{2,2}(t) + a_{12}p^4v_{1,1}(t)v_{2,3}(t) + \dots + a_{12}p^2v_{2,0}(t)v_{1,2}(t) + a_{12}p^3v_{1,2}(t)v_{2,1}(t) \end{aligned}$$

$$+a_{12}p^4v_{1,2}(t)v_{2,2}(t) \dots + a_{12}p^3v_{1,3}(t)v_{2,0}(t) + a_{12}p^4v_{1,3}(t)v_{2,1}(t). \dots + a_{12}p^4v_{1,4}(t)v_{2,0}(t) \dots] = 0 \quad (11)$$

From (10),

$$0 + pv'_{2,1}(t) + p^2v'_{2,2}(t) + p^3v'_{2,3}(t) + p^4v'_{2,4}(t) + p^5v'_{2,5}(t) + \dots - 0 + p[0 + a_2v_{2,0}(t) + a_2pv_{2,1}(t) + a_2p^2v_{2,2}(t) + a_2p^3v_{2,3}(t) + a_2p^4v_{2,4}(t) + a_2p^5v_{2,5}(t)] = 0 \quad (12)$$

Now comparing the coefficient of various powers of p in (11) & (12), we obtain

The coefficient of P¹:

$$v'_{1,1}(t) - a_1v_{1,0}(t) + a_{11}v_{1,0}^2(t) + a_{12}v_{1,0}(t)v_{2,0}(t) = 0$$

$$v'_{2,1}(t) + a_2v_{2,0}(t) = 0$$

The coefficient of P²:

$$v'_{1,2}(t) - a_1v_{1,1}(t) + a_{11}v_{1,0}(t)v_{1,1}(t) + a_{11}v_{1,0}(t)v_{1,1}(t) + a_{12}v_{1,0}(t)v_{2,1}(t) + a_{12}v_{1,1}(t)v_{2,0}(t) = 0$$

$$v'_{2,2}(t) + a_2v_{2,1}(t) = 0$$

The coefficient of P³:

$$v'_{1,3}(t) - a_1v_{1,2}(t) + a_{11}v_{1,0}(t)v_{1,2}(t) + a_{11}v_{1,1}^2(t) + a_{11}v_{1,0}(t)v_{1,2}(t) + a_{12}v_{1,0}(t)v_{2,2}(t) - a_{12}v_{1,1}(t)v_{2,1}(t) + a_{12}v_{2,0}(t)v_{1,2}(t) = 0$$

$$v'_{2,3}(t) + a_2v_{2,2}(t) = 0$$

The coefficient of P⁴:

$$v'_{1,4}(t) - a_1v_{1,3}(t) + a_{11}v_{1,0}(t)v_{1,3}(t) + a_{11}v_{1,1}(t)v_{1,2}(t) + a_{11}v_{1,1}(t)v_{1,2}(t) + a_{11}v_{1,0}(t)v_{1,3}(t) + a_{12}v_{1,0}(t)v_{2,3}(t) + a_{12}v_{1,1}(t)v_{2,2}(t) + a_{12}v_{2,1}(t)v_{1,2}(t) + a_{12}v_{2,0}(t)v_{1,3}(t) = 0$$

$$v'_{2,4}(t) + a_2v_{2,3}(t) = 0$$

Now $v_1(0) = c_1, v_2(0) = c_2$

$$v_{1,1}(t) = a_1 \int_0^t v_{1,0}(t)dt - a_{11} \int_0^t v_{1,0}^2(t)dt - a_{12} \int_0^t v_{1,0}(t)v_{2,0}(t)dt$$

$$= c_1a_1t - a_{11}c_1^2t + a_{12}c_1c_2t$$

$$\therefore v_{1,1}(t) = (a_1 - a_{11}c_1 - a_{12}c_2)c_1t$$

$$v_{2,1}(t) = -a_2 \int_0^t v_{2,0}(t) dt = -a_2 c_2 t$$

$$\therefore v_{2,1}(t) = -a_2 c_2 t$$

$$v_{1,2}(t) = a_1 \int_0^t v_{1,1}(t) dt - 2a_{11} \int_0^t v_{1,0}(t) v_{1,1}(t) dt - a_{12} \int_0^t v_{1,0}(t) v_{2,1}(t) dt$$

$$-a_{12} \int_0^t v_{1,1}(t) v_{2,0}(t) dt$$

$$= a_1(a_1 - a_{11}c_1 - a_{12}c_2)c_1 \frac{t^2}{2} - 2a_{11}c_1(a_1 - a_{11}c_1 - a_{12}c_2)c_1 \frac{t^2}{2}$$

$$+ c_1 a_2 c_2 \frac{t^2}{2} - a_{12}c_2(a_1 - a_{11}c_1 - a_{12}c_2)c_1 \frac{t^2}{2}$$

$$\therefore v_{1,2}(t) = [(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1 + a_2 a_{12}c_1 c_2] \frac{t^2}{2}$$

$$v_{2,2}(t) = -a_2 \int_0^t v_{2,1}(t) dt$$

$$= [a_2^2 c_2] \frac{t^2}{2}$$

$$\therefore v_{2,2}(t) = [a_2^2 c_2] \frac{t^2}{2}$$

$$v_{1,3}(t) = a_1 \int_0^t v_{1,2}(t) dt - 2a_{11}c_1 \int_0^t v_{1,2}(t) dt - a_{11} \int_0^t v_{1,1}^2(t) dt - a_{12}c_1 \int_0^t v_{2,2}(t) dt$$

$$-a_{12}c_2 \int_0^t v_{1,2}(t) dt - a_{12} \int_0^t v_{1,1}(t) v_{2,1}(t) dt$$

$$= (a_1 - 2a_{11}c_1 - a_{12}c_2)\{(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1$$

$$-a_{12}c_1 c_2(a_2 - a_{22}c_2)\} \frac{t^3}{6} - a_{11}(a_1 - a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1^2 \frac{t^3}{3}$$

$$-a_{12}c_1(a_2^2 c_2^2) \frac{t^3}{6} - a_{12}a_2 c_2 c_2(a_1 - a_{11}c_1 - a_{12}c_2)c_1 \frac{t^3}{3}$$

$$\therefore v_{1,3}(t) = [(a_1 - 2a_{11}c_1 - a_{12}c_2)\{(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1$$

$$+ a_{12}a_2 c_1 c_2\} + (a_1 - a_{11}c_1 - a_{12}c_2)c_1\{2a_{12}c_2(-a_2) - 2a_{11}(a_1 - a_{11}c_1 - a_{12}c_2)c_1\}$$

$$-a_{12}c_1 c_2\{(-a_2)(-a_2)\}] \frac{t^3}{6}$$

$$v_{2,3}(t) = -a_2 \int_0^t v_{2,2}(t) dt$$

$$= a_2^3 c_2 \frac{t^3}{6}$$

$$\therefore v_{2,3}(t) = a_2^3 c_2 \frac{t^3}{6}$$

$$v_{1,4}(t) = (a_1 - 2a_{11}c_1 - a_{12}c_2) \int_0^t v_{1,3}(t) dt - 2a_{11} \int_0^t v_{1,1}(t)v_{1,2}(t) dt - a_{12} \int_0^t v_{1,1}(t)v_{2,2}(t) dt \\ - a_{12} \int_0^t v_{1,2}(t)v_{2,1}(t) dt - a_{12}c_1 \int_0^t v_{2,3}(t) dt$$

$$= [(a_1 - 2a_{11}c_1 - a_{12}c_2)\{(a_1 - 2a_{11}c_1 - c_2)\{(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2) c_1$$

$$+ a_{12}c_1c_2a_2\} + (a_1 - a_{11}c_1 - a_{12}c_2)c_1\{2a_{12}c_2(-a_2)$$

$$- 2a_{11}\{(a_1 - a_{11}c_1 - a_{12}c_2)c_1\} - a_{12}c_1c_2a_2^2] \frac{t^4}{24} - 2a_{11}(a_1 - a_{11}c_1 - a_{12}c_2)c_1\{(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1 + a_{12}c_1a_2c_2\} \frac{t^4}{8} + a_{12}c_1\{(a_2$$

$$)(-a_2)c_2(-a_2)\} \frac{t^4}{24} - a_{12}c_1(a_1 - a_{11}c_1 - a_{12}c_2)[a_2^3] \frac{t^4}{8} - a_{12}a_2c_2[(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1] \frac{t^4}{8}$$

$$\therefore v_{1,4}(t) = [(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1 - a_2a_{12}c_1c_2$$

$$[(a_1 - 2a_{11}c_1 - a_{12}c_2)^2 - c_16a_{11}(a_1 - a_{11}c_1 - a_{12}c_2)] + (a_1 - 2a_{11}c_1 - a_{12}c_2)$$

$$\{2(a_1 - a_{11}c_1 - a_{12}c_1)c_1[a_{12}c_2a_2 - a_{11}(a_1 - a_{11}c_1 - a_{12}c_2)c_1] - a_{12}c_1c_2a_2^2\} + [a_2^2c_2]$$

$$[a_{12}c_1 - 3a_{12}c_1(a_1 - a_{11}c_1 - a_{12}c_2)] - a_2c_2\{[(a_1 - a_{11}c_1 - a_{12}c_2)c_1[3a_{12}(2a_{11}c_1 - a_1 - a_{12}c_2)] - a_2c_23a_{12}^2c_1\} \frac{t^4}{24}$$

$$v_{2,4}(t) = -a_2 \int_0^t v_{2,3}(t) dt$$

$$= a_2^4 c_2 \frac{t^4}{24}$$

$$\therefore v_{2,4}(t) = a_2^4 c_2 \frac{t^4}{24}$$

Up to the terms which contain maximum the power of four, we obtain

$$N_1(t) = \lim_{p \rightarrow 1} v_1(t) = \sum_{x=0}^4 v_{1,x}(t) = v_{1,0}(t) + v_{1,1}(t) + v_{1,2}(t) + v_{1,3}(t) + v_{1,4}(t)$$



$$N_1(t) = \lim_{p \rightarrow 1} v_2(t) = \sum_{x=0}^4 v_{2,x}(t) = v_{2,0}(t) + v_{2,1}(t) + v_{2,2}(t) + v_{2,3}(t) + v_{2,4}(t)$$

The solutions by Homotopy Perturbation Method are derived as

$$\begin{aligned} N_1(t) &= c_1 + [(a_1 - a_{11}c_1 - a_{12}c_2)c_1]t \\ &+ [(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1 + a_2a_{12}c_1c_2]\frac{t^2}{2} \\ &+ \{(a_1 - 2a_{11}c_1 - a_{12}c_2)[(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1 + a_2a_{12}c_1c_2] \\ &+ (a_1 - a_{11}c_1 - a_{12}c_2)c_1[-2a_2a_{12}c_2 - 2a_{11}(a_1 - a_{11}c_1 - a_{12}c_2)c_1] \\ &- a_{12}c_1c_2a_2^2\}\frac{t^3}{6} \{[(a_1 - 2a_{11}c_1 - a_{12}c_2)(a_1 - a_{11}c_1 - a_{12}c_2)c_1 \\ &+ a_2a_{12}c_1c_2][(a_1 - 2a_{11}c_1 - a_{12}c_2)^2 - 6a_{11}c_1(a_1 - a_{11}c_1 - a_{12}c_2)] \\ &+ (a_1 - 2a_{11}c_1 - a_{12}c_2)\{2(a_1 - a_{11}c_1 - a_{12}c_2)c_1a_2a_{12} - a_{11}(a_1 - a_{11}c_1 - a_{12}c_2)c_1 \\ &- a_{12}c_1c_2a_2^2\} + a_2^2[a_{12}c_1a_2 - 3a_{12}c_1(a_1 - a_{11}c_1 - a_{12}c_2)] \\ &- a_2c_2\{(a_1 - a_{11}c_1 - a_{12}c_2)c_1[3(a_1 - 2a_{11}c_1 - a_{12}c_2)a_{12}] - 3a_{12}^2c_1a_2c_2\}\}\frac{t^4}{24} \\ \therefore N_2(t) &= c_2 - a_2t + a_2^2c_2\frac{t^2}{2} + a_2^3c_2\frac{t^3}{6} + a_2^3c_2\frac{t^4}{24} \end{aligned}$$

V. CONCLUSIONS

A mathematical model of Ecological Model of Ammensalism with mortal Enemy species is constituted by a couple of first order nonlinear differential equations. A series solution of this Ammensalism is computed by Homotopy Perturbation Method.

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