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COMPARATIVE STUDY OF DIODE CLAMPED, FLYING CAPACITOR AND H-BRIDGE MULTILEVEL INVERTER HARMONICS REDUCTION

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ABSTRACT

The power electronics device which converts DC power to AC power at required output voltage and frequency level is known as inverter. The voltage source inverters produce an output voltage or a current with levels either 0 or +ve or-ve V dc. They are known as two-level inverters. Multilevel inverter is to synthesize a near sinusoidal voltage from several levels of dc voltages. Multilevel inverter has advantage like minimum harmonic distortion. Multi-level inverters are emerging as the new breed of power converter options for high power applications. They typically synthesize the stair-case voltage waveform (from several dc sources) which has reduced harmonic content. This thesis compares three different topologies of inverters (5- level inverter, Diode clamped inverter, 5-level Flying capacitor clamped inverter and 5-level Cascaded H-bridge inverter). In this model of five-level Three Phase Diode clamped inverter, Flying capacitor clamped inverter and Cascaded H-Bridge inverter has been developed using MOSFETS IGBT. Gating signals for these MOSFETS have been generated by designing comparators. In order to maintain the different voltage levels at appropriate intervals, the conduction time intervals of MOSFETS have been maintained by controlling the pulse width of gating pulses (by varying the reference signals magnitude of the comparator). The result is compared with simulation results. Simulation models (designed in SIMULINK) have been developed up to five levels and THD in all the cases have been identified.

Keywords: Multilevel, Diode Clamped, Flying Capacitor, H-Bridge, Cascade, Harmonics, Modulation, MATLAB/SIMULINK, %THD.

I. INTRODUCTION

The need for high power apparatus in industry has increased in recent years. Multilevel converters have developed as easy alternatives for such power requirements. Mostly used in medium voltage applications, multilevel converters have gained prominence since it is not feasible to connect a single power semiconductor switch directly to the grid. There are other advantages of multilevel converters such as their capability to be easily interfaced with the

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renewable energy sources such as solar power, wind power, and fuel cells. Multilevel converters consist of a group of semiconductor switches, like IGBTs, and a set of voltage source components like capacitors or independent sources. The basic concept of these converters depends on using this series of switches and sources to synthesize a stepped or staircase output voltage waveform. Therefore, they reduce the voltage stress on each device or component used. Multilevel converters play a significant role in enhancing the quality of high power distribution networks, power conditioning systems, variable speed drive systems etc because of the availability of higher number of voltage levels at the output. This helps in reducing the size of switching components which can be operated at lower switching frequencies. However, multilevel converters have their own disadvantages. Voltage sharing may not be as desired under all conditions because of the series connection of the switching devices.

II. MULTILEVEL INVERTER

1. 5-level diode clamped multilevel inverter

Diode-clamped inverters are one of the earliest designed topologies of multilevel inverters. Figure 2.1 shows a single phase five-level diode-clamped inverter. The two capacitors connected in the circuit split input voltage Vdc to obtain the midpoint voltage of the input. In a three level topology, the common point of capacitors is connected to the ground. Therefore, this circuit can also be called the neutral point clamped inverter. Diodes D1 and D2 present in the circuit help with clamping dc voltage V_{dc} to obtain different output voltage levels. There are nine allowable switching states for the given circuit to obtain five different output voltage levels +Vdc, +Vdc /2, 0, -Vdc/2, and – V_{dc} . It has to be noted that switch pairs Sa1 and Sa1', and Sa2 and Sa2' are complementary to each other. Similarly, switch pairs Sb1 and Sb1', and Sb2 and Sb2' are complementary to each other.

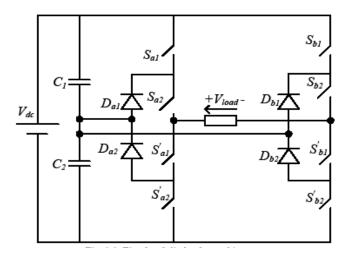


Fig. 1 Three phase diode clamped inverter.

The number of switches, capacitors, and diodes required in the circuit increases with the number of output voltage levels desired. For every additional level of voltage, it requires an extra pair of complementary switches is required

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in each limb of the circuit and also additional capacitors and clamping diodes. However, in such cases, voltage balancing of the capacitors and the cost of diodes become a practical problem. Another disadvantage of diodeclamped multilevel inverters is that they need high voltage rating diodes to block the reverse voltages.

2. 5-level flying capacitor multilevel inverters

The diodes in the diode-clamped topology can be replaced by clamping capacitors or floating capacitors to clamp the voltages. Such a topology is called flying capacitor multilevel inverter (FCMLI). FCMLI topologies are relatively new compared to the diode-clamped the cascaded H-bridge cell inverter topologies. Redundancy in the switching states is available by using flying capacitors instead of clamping diodes. This redundancy can be used to regulate the capacitor voltages and obtain the same desired level of voltage at the output. Figure2 shows a single-phase five-level FCMLI topology. The voltage across the capacitors is considered to be half of Dc source voltage Vdc. The output voltage consists of five different voltage levels + Vdc, Vdc/2, 0, -Vdc/2, and - Vdc. Similar to the other multilevel converter topologies, FCMLI also has complementary switch pairs. In the present considered circuit, switches Sa1 &Sa1 ', and Sa2 &Sa2 ' are complementary to each other. Similarly on the other limb, switches Sb1 &Sb1 ', and Sb2 &Sb2' are complementary to each other. The switching states available for such a topology are higher than that of the diode clamped. The number of voltage levels at the output can be increased by adding a pair of complementary switches and a capacitor. However, all the capacitors used in such topologies must be rated identically which can prove to be expensive and bulky in size. Single-phase five-level FCMLI topology VdcCa CbSa1Sa2

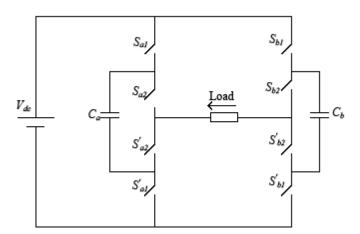


Fig.2.Three phase 5-level Flying capacitor multilevel inverter

3. Cascaded H-bridge multilevel inverter.

Cascaded H-bridge multilevel inverter topology is a series connection of two or more individual full bridge inverters. Figure 3 shows a single-phase, five-level cascaded H-bridge cell inverter realized by connecting two three

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level conventional full bridge inverters in series. Switch pairs Sa1 and Sa1', and Sa2 and Sa2' are complementary to each other. Similarly, switch pairs of the other full bridge inverter Sb1 and Sb1', and Sb2 and Sb2' are complementary to each other. The different voltage levels that can be obtained at the output terminals are +2Vdc, +Vdc, 0, Vdc, -2Vdc. If the dc voltage sources in both the inverter circuits connected in series are not equal to each other, then nine levels can be obtained at the output terminals. Thenumber of levels in the output voltage can be increased by two by adding an identical inverter in series. Cascaded H-bridge cell inverters use the least number of power electronic devices when compared to any other topology. However, they require isolated power sources in each cell which in turn requires a large isolating transformer.

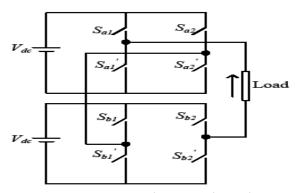


Fig.3 Three phase cascaded H-bridge multilevel inverter

The major challenge in the flying capacitor multilevel inverter topologies is the voltage regulation across the capacitors. Therefore, the appropriate selection of switching states becomes a priority in FCMLI topologies.

III. CONTROL TECHNIQUES FOR MULTILEVEL INVERTER

1. Modulation

When it comes to multilevel inverter modulation there are basically two groups of methods: modulation with fundamental switching frequency or high switching frequency PWM. For both cases a stepped output waveform is achieved, but with the high switching frequency methods the steppes are modulated with some sort of PWM. Independent of switching frequency choice there are, however, also space vector methods to choose from.

2. PWM for multilevel inverters

Multilevel PWM methods uses high switching frequency carrier waves in comparison to the reference waves to generate a sinusoidal output wave, much like in the two-level PWM case. To reduce harmonic distortions in the output signal phase-shifting techniques are used. There are several methods that change disposition of or shift multiple triangularcarrier waves. The number of carrier waves used is dependent to the number of switches to be controlled in the inverter. In addition to the two sinusoidal carrier wave modulation methods presented further down there are also two more well known alternative methods that will not be discussed in this report: Alternative Position Opposition Disposition (APOD) and Phase Opposition Disposition (POD).

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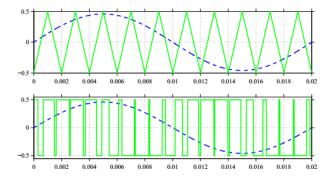


Fig.4 PWM reference (blue dashed) and triangular carrier (green solid) wave in upper plot and output voltage (green solid) eave in lower plot

3 Phase Shifted Carrier PWM

The Phase Shifted Carrier PWM (PSCPWM), Figure 5, is a multicarrier modulation strategy that has all carrier waves phase shifted from each other. It is the standard modulation strategy for the CMCI topology but is not exclusively for that topology. For a CMCI with n number of full-bridge modules in each phase-leg there are also n number of triangular carrier waves. The magnitudes for the carrier waves are modulated by the actual voltage level in the appropriate module. For the ve-level CMCI with two modules there are two triangular carrier waves, one for each module, see Figure 5 The modules create the two voltages in Figure 3.3 with PSCPWM modulation. There are also two reference waveforms for the two legs in each inverter modules that are phase shifted 180° from each other, as can be seen in Figure 5. Both reference waves are compared with both carrier waves, one reference wave is for modulation of the left full-bridge module leg switches (dashed reference wave) and the other reference wave to modulate the right full-bridge module leg switches (solid reference wave). The first triangular wave in Figure 5 is compared with the upper output voltage plot in Figure 4 (and the second triangular with the lower voltage plot). Close to 2ms in the plots it can be seen that the first triangular wave crosses one reference wave downwards, controlling the right leg switchesof the modules, turning that modules output voltage from 0 kV to -0.5 kV. Closely after the second carrier wave crosses the same reference wave (the one that controls the right leg switches in the modules) upwards turning the output voltage from -0.5 kV to 0 kV. Comparisons with the other reference wave works in the same wave, but then controlling switches in the modules left legs. As the plots suggests the two modules share the workload for all levels, no module is strictly connected to one voltage level in the output. For the CMCI this strategy cancels all carrier and sideband associated harmonics up to the 2nth carrier group.

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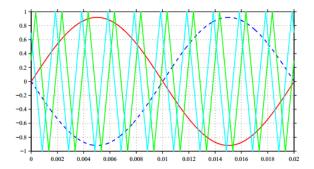


Fig.5 The carrier and reference waves for a wve-level CMCI with PSCPWM, two reference waves and two triangular waves (one for each module).

4 Phase Distortion PWM

In Phase Distortion PWM (PDPWM), Figure 6 all carrier waves are in phase. A great acknowledgment for this technique is that it is generally accepted as the method that creates the lowest harmonic distortion in line-to-line voltage. When used for an NPCMLI with *m* number of voltage levels, *m*-1 number of triangular carrier waves is used. These carrier waves have the same frequency and are arranged on top of each other, with no phase shift, so that they together span from maximum output voltage to minimum output voltage. The carrier waves amplitudes should be modulated with aspect of the current voltage magnitude for each respective voltage level, each carrier wave is connected to a specific output voltage level. If the carrier waves are not modulated in this way the correct output voltage will not be achieved if the sources voltage levels change from their supposed value (get unbalanced). If the sources voltage amplitudes change without that the carrier waves are modulated with that change the correct output voltage will not be generated during the during the correct time spans.

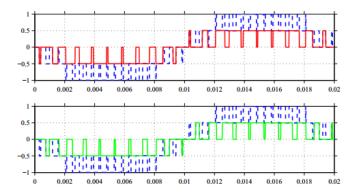


Fig.6The two module voltages, one in each plot, together with the achieved totaloutput voltage (blue dashed line in both plots)

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When one carrier wave is crossed by the reference the output wave steps one level up or down with a switch transaction. One carrier wave hence modulates the use of one voltage state. Only one level is modulated at any time, as can be seen in the in Figure 6, sincethe reference only crosses one carrier at any level. The output voltage from the PDPWM modulation with a-ve-level NPCMLI is shown in Figure 6

IV PROJECT DESIGN AND IMPLEMENTATION

1. Modelling of Five level diode clamped inverter

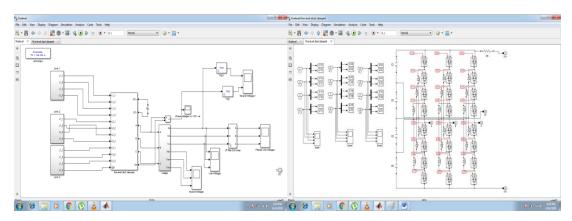


Fig. 7 Simulink model three phase 5 level diode clamped inverter & Switching block of three phase 5 level inverter.

2. Modeling Of Single Phase Flying Capacitor Multilevel Inverters

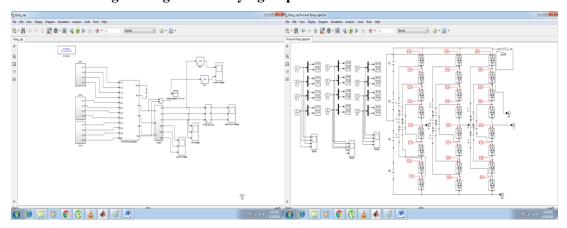


Fig.9 Simulink model of Three phase 5 level flying capacitor clamped inverter &Switching block of three phase 5 level Flying capacitor clamped inverter.

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3. Modelling of single phase cascaded H-bridge multilevel inverter.

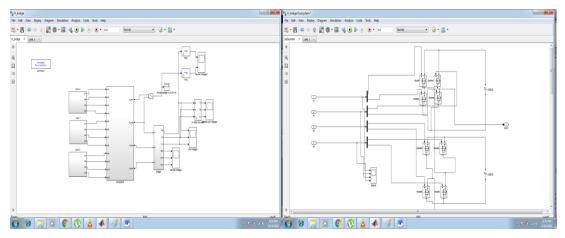


Fig.11 Three phase of a 5 level cascaded H-bridge inverter&Switching block of Three phase 5 level cascaded H-bridge inverter

V SIMULATONS & RESULT

The multi-level inverter system is a very promising device in AC power drives when both reduced content and high power are required. Up to now several multilevel topologies have been introduced. The main topologies are diode clamped inverter, flying capacitor inverter, H-bridge inverter in order to generate a high voltage waveform using low voltage devices. In this chapter, we are considering the simulation of three main topologies in multi level inverter. Here we are going to have 5 level diode clamped inverter, flying capacitor inverter, H-bridge inverter.

1. Simulation of 5 level diode clamped inverter.

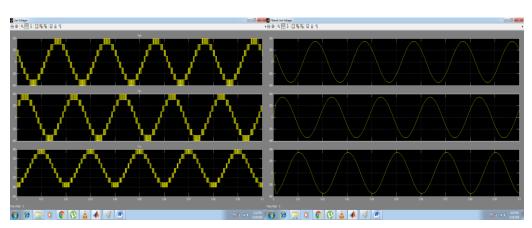


Fig.13 Output voltage without & with filtered voltage waveform of 5 level diode clamped inverter.

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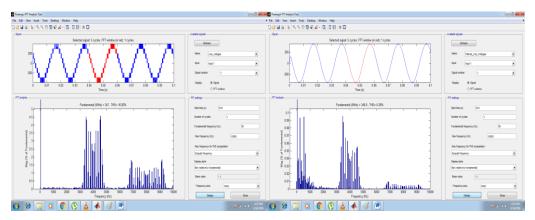


Fig.15 FFT analysis output without & with filtered voltage waveform of 5 level diode clamped inverter

2. Simulation of 5 Level Flying Capacitor Clamped Inverter

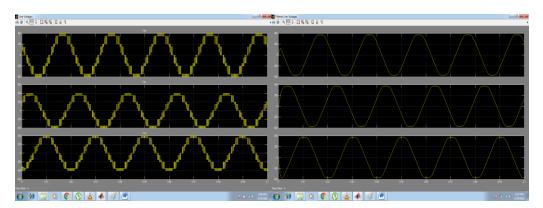


Figure 6.6 Output without & with filtered voltage of 5 level flying capacitor clamped inverter

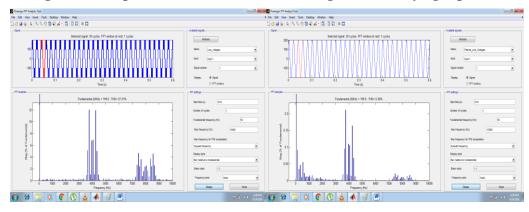


Figure 6.9 FFT analysis of output without & with filtered voltage waveform of 5 level flying capacitor clamped inverter

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3. Simulation of 5 level cascaded h-bridge inverter.

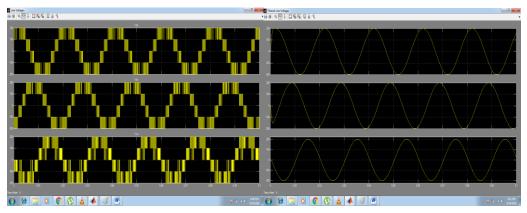


Figure 6.11 Output without & with filtered voltage waveform of 5 cascaded H- Bridge inverter.

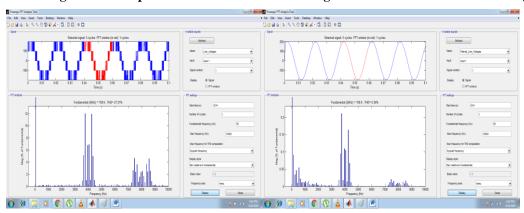


Figure 6.14 FFT analysis of Output without & with filteredvoltage waveform of 5 cascaded H- Bridge inverter.

5.1 RESULTS

From FFT analysis of the three topologies we get the total harmonic distortion (THD) as follows:

Controllers	THD of inverter output Line Voltage (%)	THD of filtered Line Voltage (%)
Diode Clamped Multilevel inverter	16.82%	0.28%
Flying Capacitor Multilevel inverter	27.21%	0.36%
H bridge Multilevel inverter	27.21%	0.36%

VI CONCLUSION &FUTURE SCOPE

This work has presented several topologies for multilevel inverters (MLI), some of them well known with applications on the market. Every topology have been described in

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detail. Several modulation techniques have also been presented which are to be used with the presented topologies. We hereby conclude that Multi-level inverters is a very promising technology in the power industry. In this project, the advantages and applications of Multi-Level Inverters are mentioned and a detailed description of different multi-level inverter topologies is presented. Single Phase H-Bridge Inverter, Diode led and Flying capacitor multi level inverter functioning is realized virtually using MATLAB SIMULINK.

A detailed Multi-Level Inverter is presented from which we concluded that the harmonic content is greatly reduced in Multi-Level Inverter and the Cascaded H-Bridge Inverter topology has advantage over the other two as it requires less number of components as compared to the other two types of inverters and so its overall weight and price is also less. This project can be extended further by increasing the number of levels in multilevel inverter. IC's can be used to generate gating pulses directly rather than designing them by using comparators and NOT gates. By using IC's, complexity in designing gate pulses can be reduced.

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